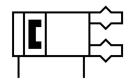
## Three-point gripper DHDS-50-A Part number: 1259495







## General operating condition **Data sheet**

Feature	Value
Size	50
Stroke per gripper jaw	6 mm
Max. interchangeability	≤0.2 mm
Max. gripper jaw angular play ax, ay	≤0.2 deg
Max. gripper jaw backlash Sz	≤0.02 mm
Rotational symmetry	≤0.2 mm
Pneumatic gripper repetition accuracy	≤0.04 mm
Number of gripper jaws	3
Mounting position	Any
Mode of operation	Double-acting
Gripper function	3-point
Structural design	Lever Positively driven motion sequence
Position sensing	For proximity sensor
Symbol	00991894
Gripping force per gripper jaw at 6 bar, opening	840 N
Gripping force per gripper jaw at 6 bar, closing	750 N
Operating pressure	2 bar 8 bar
Max. operating frequency of pneumatic gripper	≤4 Hz
Min. opening time at 6 bar	62 ms
Min. closing time at 6 bar	55 ms
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	1 - Low corrosion stress
LABS (PWIS) conformity	VDMA24364-B2-L
Suitability for the production of Li-ion batteries	Metals with more than 5% by mass of copper are excluded from use. Exception are printed circuit boards, cables, electrical connectors and coils
Ambient temperature	5 °C 60 °C
Gripping force per gripper jaw at 6 bar, opening	280 N
Gripping force per gripper jaw at 6 bar, closing	250 N
Mass moment of inertia	6.1 kgcm²
Maximum force on gripper jaw Fz, static	250 N
Maximum torque on gripper jaw, Mx static	24 Nm
Maximum torque on gripper jaw, My static	24 Nm
Maximum torque on gripper jaw, Mz static	24 Nm

Feature	Value
Relubrication interval for guidance elements	10 MioCyc
Max. mass per external gripper finger	250 g
Product weight	920 g
Type of mounting	With internal thread and dowel pin
Pneumatic connection	G1/8
Note on materials	RoHS-compliant
Cover cap material	PA
Housing material	Wrought aluminum alloy, hard-anodized
Gripper jaw material	High-alloy stainless steel