## **Servo motor EMMB-AS-60-04-S30MB**Part number: 8097184

**FESTO** 



General operating condition

## **Data sheet**

Feature	Value
Ambient temperature	-15 °C 40 °C
Note on ambient temperature	Up to 60 °C with derating of -1.5% per degree Celsius
Max. installation height	4000 m
Information on max. installation height	with 1,000 m and longer only with derating of -1.0% per 100 m
Storage temperature	-20 °C 55 °C
Relative air humidity	0 - 90 %
Conforms to standard	IEC 60034
Thermal class according to EN 60034-1	F
Max. winding temperature	155 ℃
Rating class according to EN 60034-1	S1
Temperature monitoring	Digital motor temperature transmission via Nikon A format
Motor type as per EN 60034-7	IM B5 IM V1 IM V3
Mounting position	Any
Degree of protection	IP65
Note on degree of protection	IP40 for motor shaft without rotary shaft seal IP54 for motor shaft with rotary shaft seal IP65 for motor housing without connection technology
Concentricity, coaxiality, axial runout according to DIN SPEC 42955	N
Balancing quality	G 2.5
Bearing lifetime, under nominal conditions	20000 h
Electrical connection 1, connection type	Plug
Electrical connection 1, connection technology	Connection diagram RE
Electrical connection 1, number of pins/wires	6
Electrical connection for input 1, connection pattern	00995792
Contamination level	2
Note on materials	RoHS-compliant
Corrosion resistance class (CRC)	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Vibration resistance	Transport application test with severity level 2 as per FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 2 as per FN 942017-5 and EN 60068-2-27
Certification	c UL us - Recognized (OL)
CE marking (see declaration of conformity)	As per EU EMC directive As per EU low voltage directive As per EU RoHS directive

To U	O V  In inside  Nm  7 Nm  11 Nm  00 rpm  00 rpm  000 rpm
To U Certificate issuing authority  Nominal operating voltage DC  DC nominal voltage  Type of winding switch  Number of pole pairs  Stall torque  Nominal torque  1.44  Nominal torque  1.27  Peak torque  3.81  Nominal rotary speed  Max. rotational speed  Motor nominal power  Continuous stall current  Motor nominal current  2.64  Motor nominal current  Continuous stall current  Motor nominal current  Continuous stall current	UK instructions for electrical equipment E342973 D V D V Or in inside Nm T Nm D Nm D Or pm D Or pm D Or pm
Certificate issuing authority  Nominal operating voltage DC  DC nominal voltage  Type of winding switch  Number of pole pairs  Stall torque  Nominal torque  Peak torque  Nominal rotary speed  Max. rotational speed  Motor nominal power  Continuous stall current  UL E  300  300  300  400  600  600  600  600	E342973 D V D V Ir inside Nm T Nm D Nm D O rpm D O rpm D O rpm
Nominal operating voltage DC  DC nominal voltage  Type of winding switch  Star  Number of pole pairs  Stall torque  Nominal torque  1.27  Peak torque  3.81  Nominal rotary speed  Max. rotational speed  Max. mechanical speed  Motor nominal power  Continuous stall current  Motor nominal current  300  300  300  400  600  600  600  600	O V O V Or inside O Nm O Nm O Nm O Nm O Nm O rpm O O rpm O O rpm
DC nominal voltage 300 Type of winding switch Star Number of pole pairs 3 Stall torque 1.4 I Nominal torque 1.27 Peak torque 3.81 Nominal rotary speed 3000 Max. rotational speed 6000 Max. mechanical speed 1000 Motor nominal power 400 Continuous stall current 2.6 A Motor nominal current 2.4 A	O V  Ir inside  Nm  7 Nm  11 Nm  00 rpm  00 rpm  000 rpm
Type of winding switch  Number of pole pairs  Stall torque  Nominal torque  Peak torque  Nominal rotary speed  Max. rotational speed  Motor nominal power  Continuous stall current  Motor nominal current  Star  A Star  A Good  A Go	Nm 7 Nm 11 Nm 12 Nm 13 Nm 14 Nm 15 Nm 15 Nm 16 Or pm 16 Or pm 16 Or pm
Number of pole pairs  Stall torque  1.4  Nominal torque  1.27  Peak torque  3.81  Nominal rotary speed  Max. rotational speed  Max. mechanical speed  Motor nominal power  Continuous stall current  Motor nominal current  2.4	Nm
Stall torque 1.4 l Nominal torque 1.27 Peak torque 3.81 Nominal rotary speed 3000 Max. rotational speed 6000 Max. mechanical speed 1000 Motor nominal power 400 Continuous stall current 2.6 o Motor nominal current 2.4 o	7 Nm 11 Nm 100 rpm 100 rpm 100 rpm
Nominal torque 1.27 Peak torque 3.81 Nominal rotary speed 3000 Max. rotational speed 6000 Max. mechanical speed 1000 Motor nominal power 400 Continuous stall current 2.64 Motor nominal current 2.44	7 Nm 11 Nm 100 rpm 100 rpm 100 rpm
Peak torque 3.81  Nominal rotary speed 3000  Max. rotational speed 6000  Max. mechanical speed 1000  Motor nominal power 400  Continuous stall current 2.660  Motor nominal current 2.47	21 Nm 20 rpm 20 rpm 200 rpm
Nominal rotary speed 3000  Max. rotational speed 6000  Max. mechanical speed 1000  Motor nominal power 400  Continuous stall current 2.6 of Motor nominal current 2.4 of Motor nominal current	00 rpm 00 rpm 000 rpm
Max. rotational speed 6000 Max. mechanical speed 1000 Motor nominal power 400 Continuous stall current 2.6 A Motor nominal current 2.4 A	00 rpm
Max. mechanical speed 1000 Motor nominal power 400 Continuous stall current 2.6 A Motor nominal current 2.4 A	000 rpm
Motor nominal power 400 Continuous stall current 2.6 /r Motor nominal current 2.4 /r	
Continuous stall current 2.6 Motor nominal current 2.4 Motor nominal c	0 14/
Motor nominal current 2.4 /	U W
	A
Peak current 7.2	A
1.27	A
Motor constants 0.56	62 Nm/A
Voltage constant, phase-to-phase 34 n	mVmin
Phase-phase winding resistance 5.80	Ohm
Winding inductance phase-phase 11.5	5 mH
Electric time constant 1.98	8 ms
Measuring flange 255	5 x 255 x 8 mm, aluminum
Total output inertia moment 0.42	.25 kgcm²
Product weight 1900	00 g
Permissible axial shaft load 90 N	N
Permissible radial shaft load 180	N C
Rotor position sensor Abso	solute encoder, multi-turn
Rotor position sensor for manufacturer designation MAR	R-MX50AHN00
Rotor position encoder for absolutely detectable revolutions 655.	536
Rotor position sensor interface Niko	on A-format
Rotor position sensor measuring principle Opti	tical
Rotor position encoder for DC operating voltage 5 V	
, , ,	'5 V 5.25 V
	48576
Rotor position sensor resolution 20 b	
	0 arcsec 120 arcsec
, , ,	.V GICSCC 120 GICSCC
Brake DC operating voltage 24 V	Nm
Brake power consumption 7.2 V	Nm