



AFM60B-S1AM008192

AFS/AFM60 SSI

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

| Type | Part no. |
|-------------------|----------|
| AFM60B-S1AM008192 | 1067606 |

Other models and accessories → www.sick.com/AFS_AFM60_SSI

Detailed technical data

Performance

| | |
|---|---------------------------------|
| Number of steps per revolution (max. resolution) | 8,192 (13 bit) |
| Number of revolutions | 4,096 (12 bit) |
| Max. resolution (number of steps per revolution x number of revolutions) | 13 bit x 12 bit (8,192 x 4,096) |
| Error limits G | 0.05° ¹⁾ |
| Repeatability standard deviation σ_r | 0.002° ²⁾ |

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

²⁾ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

| | |
|--|--|
| Communication interface | SSI |
| Initialization time | 50 ms ¹⁾ |
| Position forming time | < 1 μ s |
| Code type | Gray |
| Code sequence parameter adjustable | CW/CCW (V/R) parameter adjustable |
| Clock frequency | \leq 2 MHz ²⁾ |
| Set (electronic adjustment) | H-active (L = 0 - 3 V, H = 4,0 - U _s V) |
| CW/CCW (counting sequence when turning) | L-active (L = 0 - 1,5 V, H = 2,0 - U _s V) |

¹⁾ Valid positional data can be read once this time has elapsed.

²⁾ Minimum, LOW level (Clock +): 250 ns.

Electrical data

| | |
|------------------------------------|---|
| Connection type | Cable, 8-wire, universal, 5 m ¹⁾ |
| Supply voltage | 4.5 ... 32 V |
| Power consumption | \leq 0.7 W (without load) |
| Reverse polarity protection | ✓ |

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

| | |
|--|--|
| MTTFd: mean time to dangerous failure | 250 years (EN ISO 13849-1) ²⁾ |
|--|--|

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

| | |
|---------------------------------------|---|
| Mechanical design | Solid shaft, Servo flange |
| Shaft diameter | 6 mm |
| Shaft length | 10 mm |
| Weight | 0.3 kg ¹⁾ |
| Shaft material | Stainless steel |
| Flange material | Aluminum |
| Housing material | Aluminum die cast |
| Start up torque | < 0.5 Ncm (+20 °C) |
| Operating torque | < 0.3 Ncm (+20 °C) |
| Permissible shaft loading | 80 N (radial) 40 N (axial) |
| Operating speed | ≤ 9,000 min ⁻¹ ²⁾ |
| Moment of inertia of the rotor | 6.2 gcm ² |
| Bearing lifetime | 3.0 x 10 ⁹ revolutions |
| Angular acceleration | ≤ 500,000 rad/s ² |

¹⁾ Based on devices with male connector.

²⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

| | |
|--------------------------------------|--|
| EMC | According to EN 61000-6-2 and EN 61000-6-3 ¹⁾ |
| Enclosure rating | IP65, shaft side (IEC 60529) IP67, housing side (IEC 60529) ²⁾ |
| Permissible relative humidity | 90 % (Condensation not permitted) |
| Operating temperature range | -40 °C ... +100 °C ³⁾ |
| Storage temperature range | -40 °C ... +100 °C, without package |
| Resistance to shocks | 70 g, 6 ms (EN 60068-2-27) |
| Resistance to vibration | 30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6) |

¹⁾ EMC according to the standards quoted is achieved if shielded cables are used.

²⁾ For devices with male connector: with mounted mating connector.

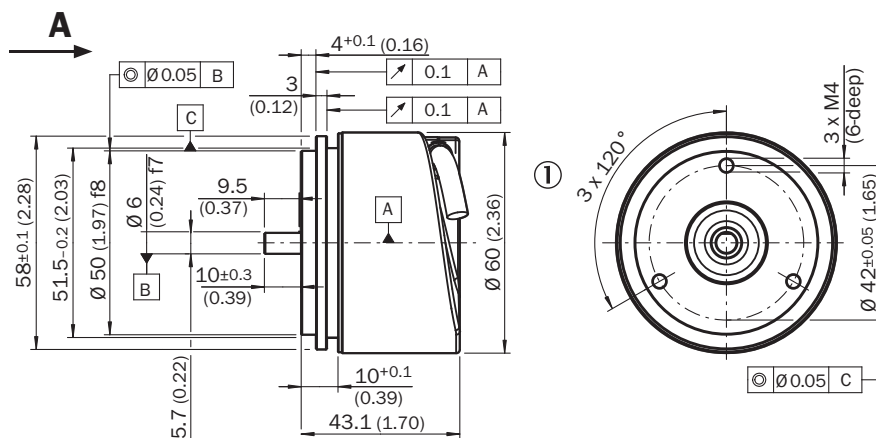
³⁾ Stationary position of the cable.

Classifications

| | |
|---------------------|----------|
| ECLASS 5.0 | 27270502 |
| ECLASS 5.1.4 | 27270502 |
| ECLASS 6.0 | 27270590 |
| ECLASS 6.2 | 27270590 |
| ECLASS 7.0 | 27270502 |
| ECLASS 8.0 | 27270502 |

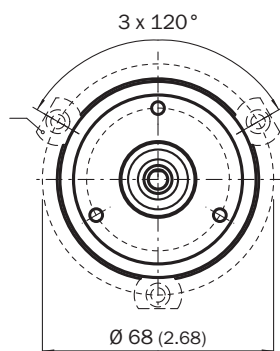
| | |
|-----------------------|----------|
| ECLASS 8.1 | 27270502 |
| ECLASS 9.0 | 27270502 |
| ECLASS 10.0 | 27270502 |
| ECLASS 11.0 | 27270502 |
| ECLASS 12.0 | 27270502 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| ETIM 8.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

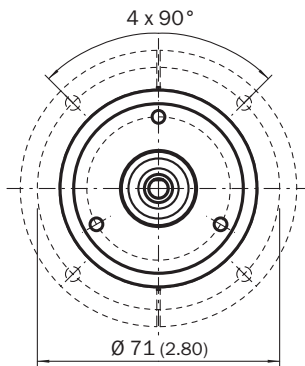
Dimensional drawing (Dimensions in mm (inch))



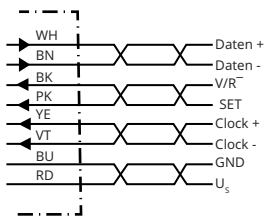
① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

Attachment specifications



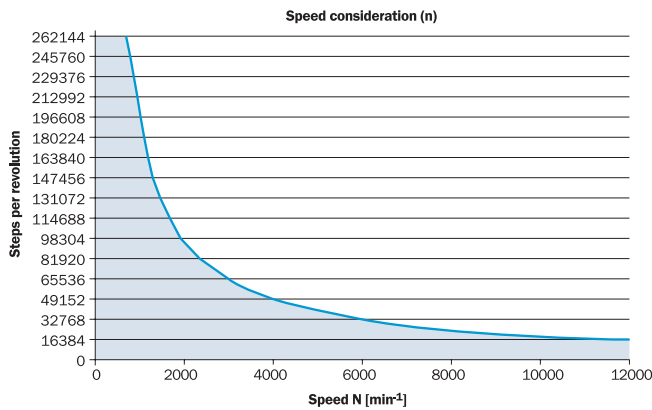


PIN assignment



| PIN | Wire colors (cable connection) | Signal | Explanation |
|-----|--------------------------------|---------|---|
| 1 | Brown | Data - | Interface signals |
| 2 | White | Data + | Interface signals |
| 3 | Black | V/R | Sequence in direction of rotation |
| 4 | Pink | SET | Electronic adjustment Interface signals |
| 5 | Yellow | Clock + | Interface signals |
| 6 | Purple | Clock - | Interface signals |
| 7 | Blue | GND | Ground connection |
| 8 | Red | U_s | Operating voltage |
| | | Screen | Screen connected to housing on encoder side. Connected to ground on control side. |








Diagrams








The maximum speed is also dependent on the shaft type.

Recommended accessories

Other models and accessories → www.sick.com/AFS_AFM60_SSI

| | Brief description | Type | Part no. |
|---|--|------------|----------|
| Other mounting accessories | | | |
|  | Servo clamps, large, for servo flange (clamps, eccentric fastener), 3 pcs, without mounting material, without mounting hardware | BEF-WK-SF | 2029166 |
| Shaft adaptation | | | |
|  | Bellows coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial ± 0.25 mm, axial ± 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub | KUP-0606-B | 5312981 |
|  | Cross-slotted coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial ± 0.3 mm, axial ± 0.2 mm, angle ± 3°; max. speed 10,000 rpm, -10° to +80 °C, max. torque 80 Ncm; material: fiber-glass reinforced polyamide, aluminum hub | KUP-0606-S | 2056406 |
| | Bar coupling, shaft diameter 6 mm / 8 mm, maximum shaft offset radial ± 0.3 mm, axial ± 0.2 mm, angle ± 3°, max. speed 10,000 rpm, torsion spring rigidity 38 Nm/wheel; material: fiber-glass reinforced polyamide, aluminum hub | KUP-0608-S | 5314179 |
|  | Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial ± 0.25 mm, axial ± 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub | KUP-0610-B | 5312982 |
|  | Double loop coupling, shaft diameter 6 mm / 10 mm, max. shaft offset: radially +/- 2,5 mm, axially +/- 3 mm, angle +/- 10 degrees; max. speed 3.000 rpm, -30 to +80 degrees Celsius, torsional spring stiffness of 25 Nm/rad | KUP-0610-D | 5326697 |
|  | Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial +/- 0.3 mm, axial +/- 0.4 mm, angular +/- 2.5°; max. speed 12,000 rpm, -10° to +80 °C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin | KUP-0610-F | 5312985 |
|  | Claw coupling, shaft diameter 6 mm / 10 mm, damping element 80 shore blue, maximum shaft offset: radial ± 0.22 mm, axial ± 1 mm angular ± 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, -30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane | KUP-0610-J | 2127056 |

| | Brief description | Type | Part no. |
|---|---|---------------|----------|
|  | Bar coupling, shaft diameter 6 mm / 10 mm, max. shaft offset: radial $\pm 0,3$ mm, axial $\pm 0,3$ mm, angular $\pm 3^\circ$; max. speed 10.000 rpm, -10° to $+80^\circ$ C, max. torque: 80 Ncm, material: fiber-glass reinforced polyamide, aluminum hub | KUP-0610-S | 2056407 |
| Others | | | |
|  | <ul style="list-style-type: none"> • Connection type head A: Male connector, M23, 12-pin, straight, A-coded • Signal type: HIPERFACE[®], SSI, Incremental, RS-422 • Description: HIPERFACE[®], SSI, Incremental, RS-422, shielded, M23 male connector • Connection systems: Solder connection | STE-2312-G | 6027537 |
|  | <ul style="list-style-type: none"> • Connection type head A: Male connector, M23, 12-pin, straight, A-coded • Signal type: HIPERFACE[®], SSI, Incremental • Description: HIPERFACE[®], SSI, Incremental, shielded, M23 female connector with central fixing (for cabinet bushing) • Connection systems: Solder connection | STE-2312-GX | 6028548 |
|  | <ul style="list-style-type: none"> • Connection type head A: Male connector, M23, 12-pin, straight, A-coded • Signal type: HIPERFACE[®], SSI, Incremental • Description: HIPERFACE[®], SSI, Incremental, shielded, Head A: male connector, M23, 12-pin, straight, for cable diameter 5.5 mm ... 10.5 mm Head B: - Operating temperature: -40° C ... $+125^\circ$ C • Connection systems: Solder connection | STE-2312-G01 | 2077273 |
|  | <ul style="list-style-type: none"> • Connection type head A: Male connector, M12, 8-pin, straight, A-coded • Signal type: Incremental • Cable: CAT5, CAT5e • Description: Incremental, shielded, Head A: male connector, M12, 8-pin, straight, A coded, shielded, for cable diameter 4 mm ... 8 mm Head B: - Operating temperature: -40° C ... $+85^\circ$ C • Connection systems: IDC quick connection • Permitted cross-section: 0.14 mm² ... 0.34 mm² | STE-1208-GA01 | 6044892 |

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SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

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