

AFM60E-S4AA000S15

AFS/AFM60 SSI

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.

Illustration may differ

Ordering information

| Type | Part no. |
|-------------------|----------|
| AFM60E-S4AA000S15 | 1081202 |

Other models and accessories → www.sick.com/AFS_AFM60_SSI



Detailed technical data

Features

| | |
|----------------------------------|---|
| Special device | ✓ |
| Specialty | Customer specific Encoder flange: face mount flange with servo slot Shaft sealing: IP67 on the shaft, starting torque < 1 Ncm Male connector, M23, 12-pin, radial, customized PIN assignment Optional accessory: customer specific half-shell servo clamps (please order separately: 2088848 BEF-WG-SF050S1) |
| Standard reference device | AFM60E-S4AA004096, 1037435 |

Performance

| | |
|---|---------------------------------|
| Number of steps per revolution (max. resolution) | 4,096 (12 bit) |
| Number of revolutions | 4,096 (12 bit) |
| Max. resolution (number of steps per revolution x number of revolutions) | 12 bit x 12 bit (4,096 x 4,096) |
| Error limits G | 0.2° ¹⁾ |
| Repeatability standard deviation σ, | 0.002° ²⁾ |

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

²⁾ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

| | |
|--|--|
| Communication interface | SSI |
| Initialization time | 50 ms ¹⁾ |
| Position forming time | < 1 μ s |
| Code type | Gray |
| Code sequence parameter adjustable | CW/CCW (V/R) parameter adjustable |
| Clock frequency | \leq 1 MHz ²⁾ |
| Set (electronic adjustment) | H-active (L = 0 - 3 V, H = 4,0 - U _s V) |
| CW/CCW (counting sequence when turning) | L-active (L = 0 - 1,5 V, H = 2,0 - U _s V) |

¹⁾ Valid positional data can be read once this time has elapsed.

²⁾ Minimum, LOW level (Clock +): 250 ns.

Electrical data

| | |
|--|--|
| Connection type | Male connector, M23, 12-pin, radial |
| Supply voltage | 4.5 ... 32 V DC |
| Power consumption | ≤ 0.7 W (without load) |
| Reverse polarity protection | ✓ |
| MTTFd: mean time to dangerous failure | 250 years (EN ISO 13849-1) ¹⁾ |

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

| | |
|---------------------------------------|---|
| Mechanical design | Solid shaft, face mount flange |
| Shaft diameter | 10 mm |
| Shaft length | 19 mm |
| Weight | 0.3 kg ¹⁾ |
| Shaft material | Stainless steel |
| Flange material | Aluminum |
| Housing material | Aluminum die cast |
| Start up torque | < 0.5 Ncm (+20 °C) |
| Operating torque | < 0.3 Ncm (+20 °C) |
| Permissible shaft loading | 80 N (radial) 40 N (axial) |
| Operating speed | ≤ 9,000 min ⁻¹ ²⁾ |
| Moment of inertia of the rotor | 6.2 gcm ² |
| Bearing lifetime | 3.0 x 10 ⁹ revolutions |
| Angular acceleration | ≤ 500,000 rad/s ² |

¹⁾ Based on devices with male connector.

²⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

| | |
|--------------------------------------|--|
| EMC | According to EN 61000-6-2 and EN 61000-6-3 ¹⁾ |
| Enclosure rating | IP65, shaft side (IEC 60529) IP67, housing side (IEC 60529) ²⁾ |
| Permissible relative humidity | 90 % (Condensation not permitted) |
| Operating temperature range | 0 °C ... +85 °C |
| Storage temperature range | -40 °C ... +100 °C, without package |
| Resistance to shocks | 50 g, 6 ms (EN 60068-2-27) |
| Resistance to vibration | 20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6) |

¹⁾ EMC according to the standards quoted is achieved if shielded cables are used.

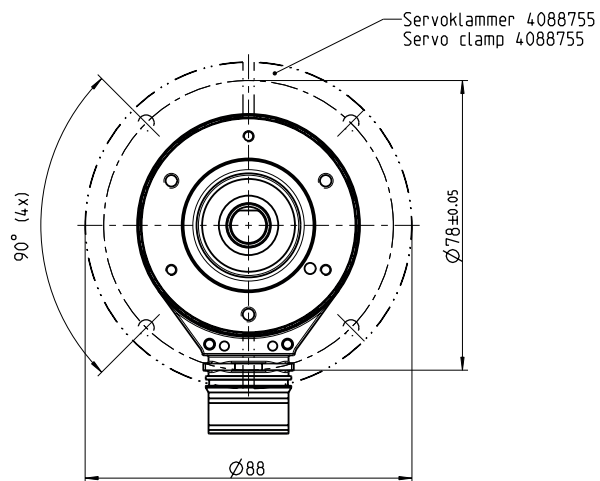
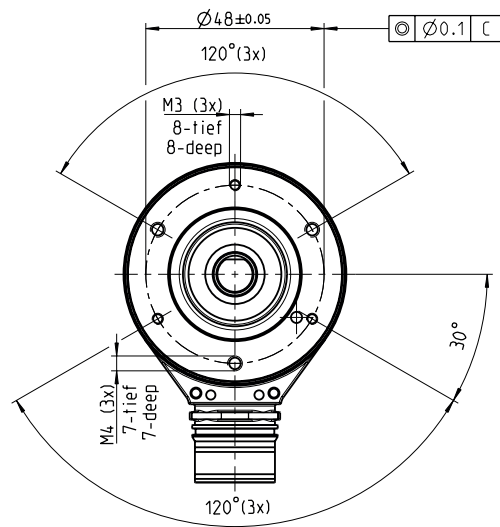
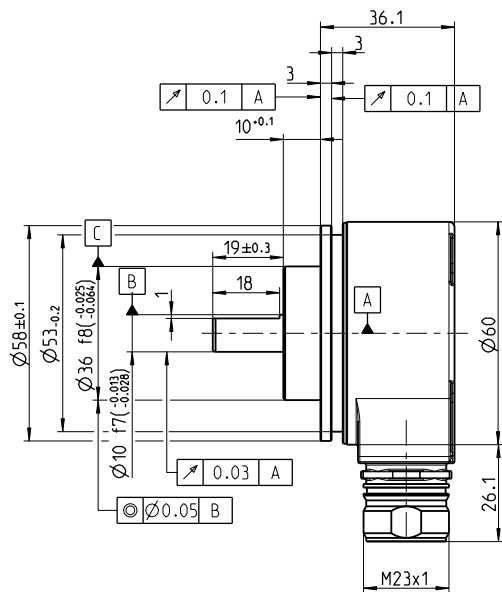
²⁾ For devices with male connector: with mounted mating connector.

Classifications

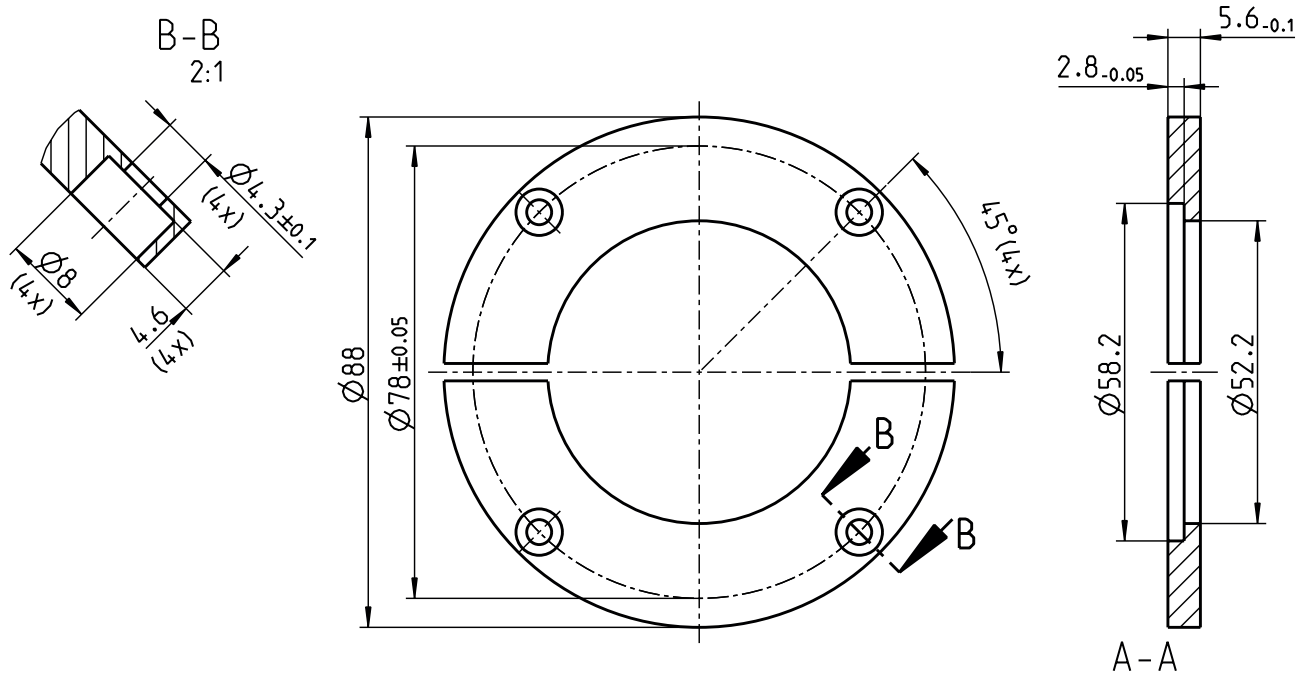
| | |
|---------------------|----------|
| ECLASS 5.0 | 27270502 |
| ECLASS 5.1.4 | 27270502 |
| ECLASS 6.0 | 27270590 |

| | |
|-----------------------|----------|
| ECLASS 6.2 | 27270590 |
| ECLASS 7.0 | 27270502 |
| ECLASS 8.0 | 27270502 |
| ECLASS 8.1 | 27270502 |
| ECLASS 9.0 | 27270502 |
| ECLASS 10.0 | 27270502 |
| ECLASS 11.0 | 27270502 |
| ECLASS 12.0 | 27270502 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| ETIM 8.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

Dimensional drawing (Dimensions in mm (inch))



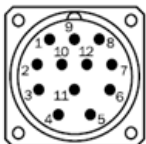
Half-shell servo clamps, 2088848 BEF-WG-SF050S1 (not included in scope of delivery of the Encoder, please order separately)



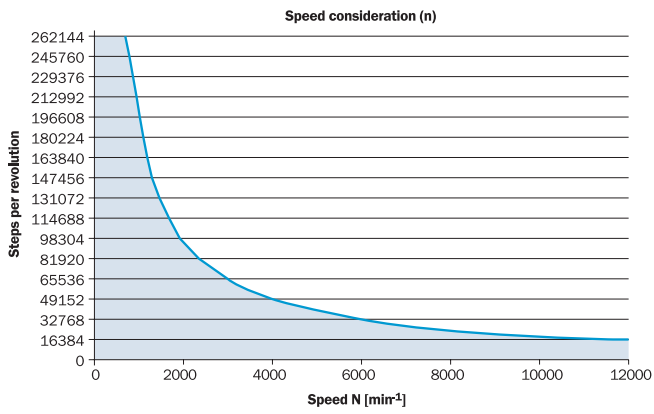
PIN assignment

Connector M23, 12-pin Ssi/Gray

| PIN | Signal | Explanation |
|-----|----------------|---|
| 1 | GND | Ground connection |
| 2 | Data + | Interface signal |
| 3 | Clock + | Interface signal |
| 4 | N.C. | Not connected |
| 5 | CW/CCW_ | Counting sequence when turning |
| 6 | N.C. | Not connected |
| 7 | N.C. | Not connected |
| 8 | U _S | Supply voltage |
| 9 | N.C. | Not connected |
| 10 | Data- | Interface signal |
| 11 | Clock - | Interface signal |
| 12 | SET | Electronic adjustment |
| | Screen | Screen on the encoder side connected to the housing. On the control side connected to earth |



Diagrams



The maximum speed is also dependent on the shaft type.

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