

AHM36A-BAQK014x12

AHS/AHM36

ABSOLUTE ENCODERS





Ordering information

Туре	Part no.
AHM36A-BAQK014x12	1101574

Other models and accessories → www.sick.com/AHS_AHM36

Illustration may differ





Detailed technical data

Performance

Number of steps per revolution (max. resolution)	16,384 (14 bit)
Number of revolutions	4,096 (12 bit)
$\label{eq:max} \begin{tabular}{ll} \textbf{Max. resolution (number of steps per revolution x number of revolutions)} \end{tabular}$	14 bit x 12 bit (16,384 x 4,096)
Error limits G	0.35° (at 20 °C) ¹⁾
Repeatability standard deviation $\boldsymbol{\sigma_{r}}$	0.2° (at 20 °C) ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

Interfaces

Communication interface	IO-Link
Communication Interface detail	IO-Link V1.1 / COM3 (230,4 kBaud)
Initialization time	2 s ¹⁾
Cycle time	≤ 3.2 ms
Smart Sensor	Efficient communication, Enhanced Sensing, diagnosis
Process data	Position, speed, electronic cams, limit values, linear position, linear speed, errors and warnings, switching signals on pin $\bf 2$
Parameterising data	Number of steps per revolution Number of revolutions PRESET Counting direction Sampling rate for speed calculation Unit for output of the speed value Round axis functionality Electronic cams(2 channels x 8 cams) Limit values Linear measuring length per 360° Pin 2 configuration
Available diagnostics data	Minimum and maximum temperature Maximumspeed Power-on counter

 $^{^{1)}\,\}mathrm{Valid}$ positional data can be read once this time has elapsed.

 $^{^{2)}}$ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

	Operatinghours counter power-on/motion Counter of direction changes/number of movements cw/number of movements ccw Minimum andmaximum operating voltage Distance covered
Status information	Via status LED
Switching input/Switching output	√
Pin 2 input frequency	≤ 100 Hz
Output frequency pin 2	≤ 100 Hz

 $^{^{1)}\,\}mbox{\sc Valid}$ positional data can be read once this time has elapsed.

Electrical data

Connection type	Cable, 4-wire, universal, 1.5 m
Supply voltage	18 30 V
Power consumption	≤ 1.5 W
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	240 years (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	6 mm
Weight	0.12 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Zinc
Start up torque	< 1 Ncm (+20 °C)
Operating torque	< 1 Ncm (+20 °C)
Permissible movement static	\pm 0.3 mm, \pm 0.3 mm (radial, axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.1 mm (axial)
Operating speed	≤ 6,000 min ⁻¹
Moment of inertia of the rotor	15 gcm ²
Bearing lifetime	2.0 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{^{1)}}$ Based on devices with male connector.

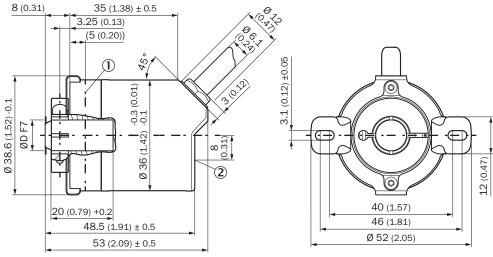
Ambient data

EMC	According to EN 61000-6-2, EN 61000-6-3 and EN 61131-9
Enclosure rating	IP66 (IEC 60529) IP67 (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +85 °C
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)

Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)
Classifications	
ECLASS 5.0	27270502
ECLASS 5.1.4	27270502
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270502
ECLASS 8.0	27270502
ECLASS 8.1	27270502
ECLASS 9.0	27270502
ECLASS 10.0	27270502
ECLASS 11.0	27270502
ECLASS 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Blind hollow shaft, cable

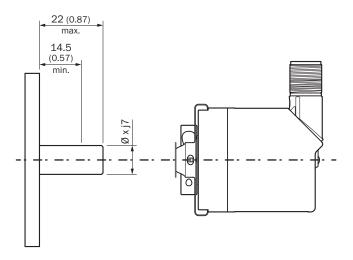


- Measuring point for operating temperature
- ② Measuring point for vibrations

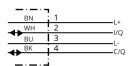
Туре	Shaft diameter Ø D F7
AHx36x-BAxxxxxxxx	6 mm
AHx36x-BBxxxxxxxx	8 mm
AHx36x-BCxxxxxxxx	1/4"
AHx36x-BDxxxxxxxx	10 mm

Туре	Shaft diameter Ø D F7
AHx36x-BKxxxxxxxx	3/8"

Attachment specifications



PIN assignment



PIN	Wire color	Signal	Function		
			Basic	Advanced	Advanced Smart Task
1	Brown	L+	Encoder supply voltage 18-30 V (+Us)		
2	White	I/Q	Not connected - no function	Multifunctional pin (configurable as switching input or switching output)	
3	Blue	Ŀ	Encoder supply voltage 0 V (GND)		
4	Black	C/Q	IO-Link communication		
			-		Switching output (SIO mode)

Recommended accessories

Other models and accessories → www.sick.com/AHS_AHM36

	Brief description	Туре	Part no.		
Flanges					
	Standard stator coupling, AHS/AHM36	BEF-DS16-AHX	2108615		
Others					
	Connection type head A: Female connector, M12, 4-pin, straight, A-coded Description: Unshielded, Head A: female connector, M12, 4-pin, straight, unshielded, for power supply, for cable diameter 4 mm 6 mm Head B: - Connection systems: Screw-type terminals Permitted cross-section: ≤ 0.75 mm²	DOS-1204-G	6007302		
10 10	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Male connector, M12, 4-pin, straight, A-coded Signal type: Sensor/actuator cable Cable: 2 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 020UB3M2A14	2096000		
66	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Male connector, M12, 4-pin, straight, A-coded Signal type: Sensor/actuator cable Cable: 5 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 050UB3M2A14	2096001		
66	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Male connector, M12, 4-pin, straight, A-coded Signal type: Sensor/actuator cable Cable: 10 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 100UB3M2A14	2096002		
No.	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Flying leads Signal type: Sensor/actuator cable Cable: 2 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 020UB3XLEAX	2095607		
	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Flying leads Signal type: Sensor/actuator cable Cable: 5 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 050UB3XLEAX	2095608		
	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Flying leads Signal type: Sensor/actuator cable Cable: 10 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 100UB3XLEAX	2095609		

SICK AT A GLANCE

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