

# AHM36A-S1CK014x12

AHS/AHM36

**ABSOLUTE ENCODERS** 





#### Ordering information

Туре	Part no.
AHM36A-S1CK014x12	1065994

Other models and accessories → www.sick.com/AHS\_AHM36

Illustration may differ









#### Detailed technical data

#### Performance

Number of steps per revolution (max. resolution)	16,384 (14 bit)
Number of revolutions	4,096 (12 bit)
$\label{eq:max} \begin{tabular}{ll} Max. resolution (number of steps per revolution x number of revolutions) \end{tabular}$	14 bit x 12 bit (16,384 x 4,096)
Error limits G	0.35° (at 20 °C) <sup>1)</sup>
Repeatability standard deviation $\boldsymbol{\sigma}_{r}$	0.2° (at 20 °C) <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

#### Interfaces

Communication interface	CANopen
Data protocol	CANopen CiA DS-301 V4.02, CiA DSP-305 LSS, Encoder Profile: - CIA DS-406, V3.2 Class C2
Address setting	0 127, default: 5
Data transmission rate (baud rate)	20 kbit/s 1,000 kbit/s, default: 125 kbit/s
Initialization time	2 s <sup>1)</sup>
Process data	Position, speed, Temperature
Parameterising data	Number of steps per revolution Number of revolutions PRESET Counting direction Sampling rate for speed calculation Unit for output of the speed value Round axis functionality Electronic cams(2 channels x 8 cams)
Available diagnostics data	Minimum and maximum temperature Maximumspeed Power-on counter Operatinghours counter power-on/motion

 $<sup>^{1)}</sup>$  Valid positional data can be read once this time has elapsed.

 $<sup>^{2)}</sup>$  In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

<sup>&</sup>lt;sup>2)</sup> See accessories.

	Counter of direction changes/number of movements cw/number of movements ccw Minimum andmaximum operating voltage
Status information	CANopen status via status LED
Bus termination	Via external terminator <sup>2)</sup>

 $<sup>^{1)}\,\</sup>mathrm{Valid}$  positional data can be read once this time has elapsed.

#### Electrical data

Connection type	Cable, 5-wire, universal, 1.5 m	
Supply voltage	10 30 V	
Power consumption	≤ 1.5 W (without load)	
Reverse polarity protection	✓	
MTTFd: mean time to dangerous failure	270 years (EN ISO 13849-1) <sup>1)</sup>	

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Mechanical data

Mechanical design	Solid shaft, Servo flange
Shaft diameter	6 mm
Shaft length	12 mm
Weight	$0.12  \mathrm{kg}^{ 1)}$
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Zinc
Material, cable	PUR
Start up torque	1 Ncm (+20 °C)
Operating torque	< 1 Ncm (+20 °C)
Permissible shaft loading	40 N (radial) 20 N (axial)
Operating speed	≤ 6,000 min <sup>-1 2)</sup>
Moment of inertia of the rotor	2.5 gcm <sup>2</sup>
Bearing lifetime	3.6 x 10^8 revolutions
Angular acceleration	≤ 500,000 rad/s²

<sup>1)</sup> Based on devices with male connector.

#### Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP66 (IEC 60529) IP67 (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +85 °C
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)

<sup>&</sup>lt;sup>2)</sup> See accessories.

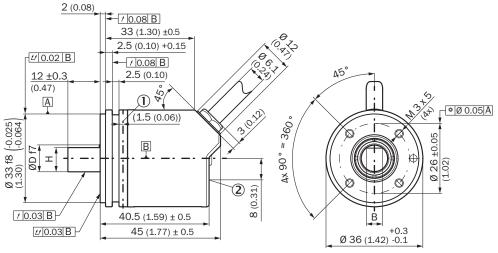
 $<sup>^{2)}</sup>$  Allow for self-heating of 3.5 K per 1,000 rpm when designing the operating temperature range.

#### Classifications

ECLASS 5.0	27270502
ECLASS 5.1.4	27270502
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270502
ECLASS 8.0	27270502
ECLASS 8.1	27270502
ECLASS 9.0	27270502
ECLASS 10.0	27270502
ECLASS 11.0	27270502
ECLASS 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

#### Dimensional drawing (Dimensions in mm (inch))

Solid shaft, servo flange, cable

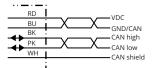


- ① Measuring point for operating temperature
- ② Measuring point for vibrations

Туре	Shaft diameter Ø D f7	В	н
AHx36x-S1xxxxxxxx AHx36x-S3xxxxxxxx	6 mm	3,6 mm	5,4 mm
AHx36x-S9xxxxxxx AHx36x-S5xxxxxxxx	8 mm	3,9 mm	7,5 mm
AHx36x-S2xxxxxxx AHx36x-S4xxxxxxx AHx36x-SCxxxxxxxx	10 mm	6 mm	9 mm

Туре	Shaft diameter Ø D f7	В	Н
AHx36x-SAxxxxxxxx AHx36x-S8xxxxxxxxx	1/4"	3,85 mm	5,7 mm
AHx36x-SBxxxxxxxx AHx36x-S7xxxxxxxx	3/8"	4,35 mm	9 mm

### PIN assignment



PIN	Signal	Wire colors (cable connection)	Function
1	CAN Shield	White	Screen
2	VDC	Red	Supply voltage Encoder 10 V DC 30 V DC
3	GND/CAN GND	Blue	0 V (GND)
4	CAN high	Black	CAN signal
5	CAN low	Pink	CAN signal
Housing	-	-	Screen

#### Recommended accessories

Other models and accessories → www.sick.com/AHS\_AHM36

	Brief description	Туре	Part no.
Programming			
SX Y	Hand-held programming device for the programmable SICK AHS/AHM36 CANopen encoders, TMS/TMM61 CANopen inclination sensors, TMS/TMM88 CANopen, TMS/TMM88 Analog, and wire draw encoders with AHS/AHM36 CANopen. Compact dimensions, low weight, and intuitive operation.	PGT-12-Pro	1076313
Shaft adaptat	tion		
	Bellows coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial $\pm$ 0.25 mm, axial $\pm$ 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0606-B	5312981
	Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial $\pm$ 0.25 mm, axial $\pm$ 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0610-B	5312982
	Double loop coupling, shaft diameter 6 mm $\!\!/$ 10 mm, max. shaft offset: radially +/- 2,5 mm, axially +/-3 mm, angle +/- 10 degrees;max. speed 3.000 rpm, -30 to +80 degrees Celsius, torsional spring stiffness of 25 Nm/rad	KUP-0610-D	5326697
(i	Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial +/- 0.3 mm, axial +/- 0.4 mm, angular +/- 2.5°; max. speed 12,000 rpm, $-10^\circ$ to +80 $^\circ$ C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin	KUP-0610-F	5312985

	Brief description	Туре	Part no.
40	Claw coupling, shaft diameter 6 mm $/$ 10 mm, damping element 80 shore blue, maximum shaft offset: radial $\pm$ 0.22 mm, axial $\pm$ 1 mm angular $\pm$ 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, –30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0610-J	2127056
Others			
	<ul> <li>Connection type head A: Flying leads</li> <li>Connection type head B: Flying leads</li> <li>Signal type: CANopen, DeviceNet™</li> <li>Cable: 4-wire, twisted pair</li> <li>Description: CANopen, DeviceNet™, shielded</li> <li>Note: Wire shield Al-Pt film, overall shield C-screen tin-plated</li> </ul>	LTG-2804-MW	6028328
	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, X-coded</li> <li>Signal type: CANopen, DeviceNet™</li> <li>Description: CANopen, DeviceNet™, shielded, Head A: female connector, M12, 5-pin, straight, shielded, for cable diameter 4.5 mm 7 mm Head B: -</li> <li>Connection systems: Screw-type terminals</li> <li>Permitted cross-section: ≤ 0.75 mm²</li> </ul>	DOS-1205-GA	6027534
Co	<ul> <li>Connection type head A: Male connector, M12, 5-pin, straight, A-coded</li> <li>Signal type: CANopen, DeviceNet™</li> <li>Description: CANopen, DeviceNet™, shielded, Head A: male connector, M12, 5-pin, straight, A coded, shielded, for cable diameter 4 mm 8 mm Head B: -</li> <li>Connection systems: Screw-type terminals</li> <li>Permitted cross-section: ≤ 0.75 mm²</li> </ul>	STE-1205-GA	6027533
	<ul> <li>Connection type head A: Male connector, M12, 5-pin, straight</li> <li>Signal type: CANopen</li> <li>Description: CANopen, unshielded, CAN male connector, with terminating resistor</li> </ul>	CAN male connector	6021167
	<ul> <li>Connection type head A: Female connector, M12, 5-pin, A-coded</li> <li>Connection type head B: Male connector, M12, 5-pin, A-coded</li> <li>Connection type head C: Female connector, M12, 5-pin, A-coded</li> <li>Description: T-piece for simultaneous connection to sender and receiver, splits the cable from the control cabinet to the sender and receiver</li> <li>Note: 5-pin</li> </ul>	DSC- 1205T000025KM0	6030664
1.66	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, A-coded</li> <li>Connection type head B: Female connector, M12, 5-pin, straight, A-coded</li> <li>Signal type: CAN, Power</li> <li>Cable: 0.5 m, 5-wire</li> <li>Description: CAN, Power, Y-CAN cable</li> </ul>	Y-CAN cable	6027647
No.	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, A-coded</li> <li>Connection type head B: Flying leads</li> <li>Signal type: Fieldbus, CANopen, DeviceNet™</li> <li>Cable: 2 m, 4-wire, PUR, halogen-free</li> <li>Description: Fieldbus, CANopen, DeviceNet™, shielded</li> <li>Application: Drag chain operation, Zones with oils and lubricants</li> </ul>	YF2A15- 020C1BXLEAX	2106283
No	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, A-coded</li> <li>Connection type head B: Flying leads</li> <li>Signal type: Fieldbus, CANopen, DeviceNet™</li> <li>Cable: 5 m, 4-wire, PUR, halogen-free</li> <li>Description: Fieldbus, CANopen, DeviceNet™, shielded</li> <li>Application: Drag chain operation, Zones with oils and lubricants</li> </ul>	YF2A15- 050C1BXLEAX	2106284
No.	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, A-coded</li> <li>Connection type head B: Flying leads</li> <li>Signal type: Fieldbus, CANopen, DeviceNet™</li> <li>Cable: 10 m, 4-wire, PUR, halogen-free</li> <li>Description: Fieldbus, CANopen, DeviceNet™, shielded</li> <li>Application: Drag chain operation, Zones with oils and lubricants</li> </ul>	YF2A15- 100C1BXLEAX	2106286

## AHM36A-S1CK014x12 | AHS/AHM36

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	Brief description	Туре	Part no.
to to	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, A-coded</li> <li>Connection type head B: Male connector, M12, 5-pin, straight, A-coded</li> <li>Signal type: Fieldbus, CANopen, DeviceNet™</li> <li>Cable: 2 m, 4-wire, PUR, halogen-free</li> <li>Description: Fieldbus, CANopen, DeviceNet™, shielded</li> <li>Application: Drag chain operation, Zones with oils and lubricants</li> </ul>	YF2A15- 020C1BM2A15	2106279
10 10	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, A-coded</li> <li>Connection type head B: Male connector, M12, 5-pin, straight, A-coded</li> <li>Signal type: Fieldbus, CANopen, DeviceNet™</li> <li>Cable: 5 m, 4-wire, PUR, halogen-free</li> <li>Description: Fieldbus, CANopen, DeviceNet™, shielded</li> <li>Application: Drag chain operation, Zones with oils and lubricants</li> </ul>	YF2A15- 050C1BM2A15	2106281
10 10	<ul> <li>Connection type head A: Female connector, M12, 5-pin, straight, A-coded</li> <li>Connection type head B: Male connector, M12, 5-pin, straight, A-coded</li> <li>Signal type: Fieldbus, CANopen, DeviceNet™</li> <li>Cable: 10 m, 4-wire, PUR, halogen-free</li> <li>Description: Fieldbus, CANopen, DeviceNet™, shielded</li> <li>Application: Drag chain operation, Zones with oils and lubricants</li> </ul>	YF2A15- 100C1BM2A15	2106282
	<ul> <li>Connection type head A: Female connector, terminal box, 8-pin, straight</li> <li>Connection type head B: Female connector, D-Sub, 9-pin, straight</li> <li>Signal type: CANopen</li> <li>Cable: 0.4 m</li> <li>Description: CANopen, shielded, Adapter cable for encoders with CANopen interface and cable outlet</li> </ul>	DDL-0D04-G0M5BC9	2083355

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SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

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