



AHM36A-S5QC014x12

AHS/AHM36

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	Part no.
AHM36A-S5QC014x12	1101533

Other models and accessories → www.sick.com/AHS_AHM36

Detailed technical data

Performance

Number of steps per revolution (max. resolution)	16,384 (14 bit)
Number of revolutions	4,096 (12 bit)
Max. resolution (number of steps per revolution x number of revolutions)	14 bit x 12 bit (16,384 x 4,096)
Error limits G	0.35° (at 20 °C) ¹⁾
Repeatability standard deviation σ_r	0.2° (at 20 °C) ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

²⁾ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

Communication interface	IO-Link
Communication Interface detail	IO-Link V1.1 / COM3 (230,4 kBaud)
Initialization time	2 s ¹⁾
Cycle time	≤ 3.2 ms
Smart Sensor	Efficient communication, Enhanced Sensing, diagnosis
Process data	Position, speed, electronic cams, limit values, linear position, linear speed, errors and warnings, switching signals on pin 2
Parameterising data	Number of steps per revolution Number of revolutions PRESET Counting direction Sampling rate for speed calculation Unit for output of the speed value Round axis functionality Electronic cams(2 channels x 8 cams) Limit values Linear measuring length per 360° Pin 2 configuration

¹⁾ Valid positional data can be read once this time has elapsed.

Available diagnostics data	Minimum and maximum temperature Maximum speed Power-on counter Operating hours counter power-on/motion Counter of direction changes/number of movements cw/number of movements ccw Minimum and maximum operating voltage Distance covered
Status information	Via status LED
Switching input/Switching output	✓
Pin 2 input frequency	≤ 100 Hz
Output frequency pin 2	≤ 100 Hz

¹⁾ Valid positional data can be read once this time has elapsed.

Electrical data

Connection type	Male connector, M12, 4-pin, universal
Supply voltage	18 ... 30 V
Power consumption	≤ 1.5 W
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	240 years (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Solid shaft, face mount flange
Shaft diameter	8 mm
Shaft length	12 mm
Weight	0.12 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Zinc
Start up torque	< 1 Ncm (+20 °C)
Operating torque	< 1 Ncm (+20 °C)
Permissible shaft loading	40 N (radial) 20 N (axial)
Operating speed	≤ 6,000 min ⁻¹
Moment of inertia of the rotor	2.5 gcm ²
Bearing lifetime	3.6 x 10 ⁸ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Based on devices with male connector.

Ambient data

EMC	According to EN 61000-6-2, EN 61000-6-3 and EN 61131-9
Enclosure rating	IP66 (IEC 60529) IP67 (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C ... +85 °C

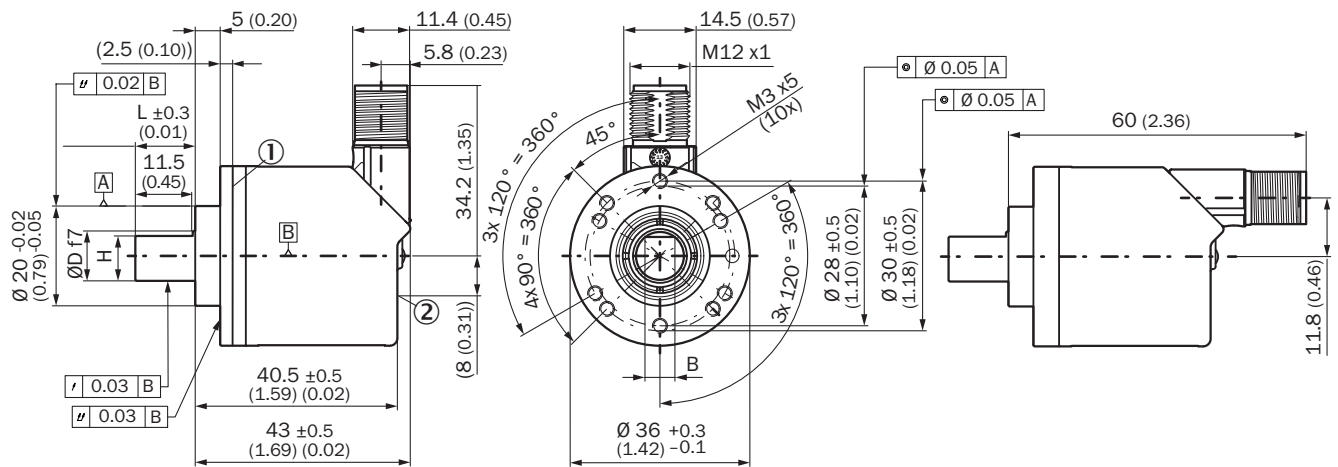
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

Classifications

ECLASS 5.0	27270502
ECLASS 5.1.4	27270502
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270502
ECLASS 8.0	27270502
ECLASS 8.1	27270502
ECLASS 9.0	27270502
ECLASS 10.0	27270502
ECLASS 11.0	27270502
ECLASS 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Solid shaft, face mount flange, male connector



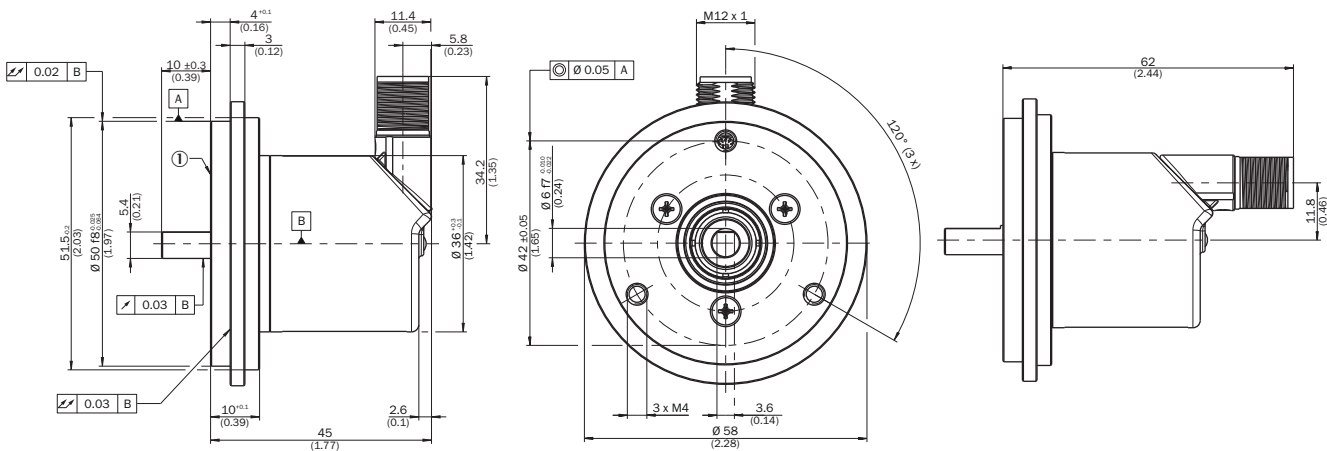
- ① Measuring point for operating temperature
- ② Measuring point for vibrations

Type	Shaft diameter Ø D f7	B	H
AHx36x-S1xxxxxxxx AHx36x-S3xxxxxxxx	6 mm	3,6 mm	5,4 mm
AHx36x-S9xxxxxxxx	8 mm	3,9 mm	7,5 mm

Type	Shaft diameter Ø D f7	B	H
AHx36x-S5xxxxxxx			
AHx36x-S2xxxxxxx AHx36x-S4xxxxxxx AHx36x-SCxxxxxxx	10 mm	6 mm	9 mm
AHx36x-SAxxxxxxx AHx36x-S8xxxxxxx	1/4"	3,85 mm	5,7 mm
AHx36x-SBxxxxxxx AHx36x-S7xxxxxxx	3/8"	4,35 mm	9 mm

Attachment specifications

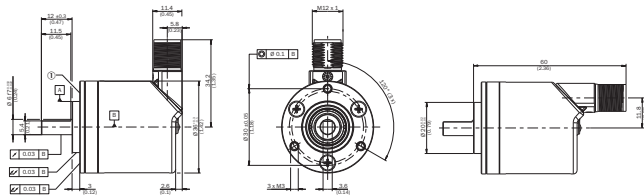
Solid shaft, face mount flange with flange adapter, centering collar D20 on D50 (BEF-FA-020-050, 2072297)



Order example for 6 mm shaft diameter: AHx36x-S3xx0xxxxx + BEF-FA-020-050 (adapter is not pre-assembled)

① Measuring point for operating temperature

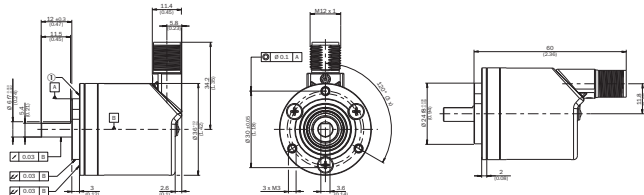
Solid shaft, face mount flange with flange adapter, centering collar D20 on D36, 2 mm high (BEF-FA-020-036-002, 2072296)



Order example for 6 mm shaft diameter: AHx36x-S3xx0xxxxx + BEF-FA-020-036-002 (adapter is not pre-assembled)

① Measuring point for operating temperature

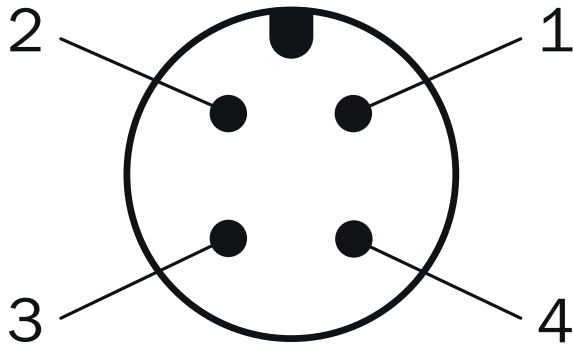
Solid shaft, face mount flange with flange adapter, centering collar D20 on D24 (BEF-FA-020-024, 2072294)



Order example for 6 mm shaft diameter: AHx36x-S3xx0xxxxx + BEF-FA-020-024 (adapter is not pre-assembled)

① Measuring point for operating temperature




PIN assignment









PIN	Wire color	Signal	Function		
			Basic	Advanced	Advanced Smart Task
1	Brown	L+	Encoder supply voltage 18-30 V (+Us)		
2	White	I/Q	Not connected - no function	Multifunctional pin (configurable as switching input or switching output)	
3	Blue	L-	Encoder supply voltage 0 V (GND)		
4	Black	C/Q	IO-Link communication		Switching output (SIO mode)

Recommended accessories

Other models and accessories → www.sick.com/AHS_AHM36

	Brief description	Type	Part no.
Shaft adaptation			
	Double loop coupling, shaft diameter 8 mm / 10 mm, max. shaft offset: radially +/- 0,25 mm, axially +/-0,4 mm, angle +/- 4 degrees;max. speed 10.000 rpm, -30 to +120 degrees Celsius, torsional spring stiffness of 150 Nm/rad	KUP-0810-D	5326704
	Claw coupling, shaft diameter 8 mm / 10 mm, damping element 80 shore blue, maximum shaft offset: radial ± 0.22 mm, axial ± 1 mm angular ± 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, -30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0810-J	2128267
Others			
	<ul style="list-style-type: none"> Connection type head A: Female connector, M12, 4-pin, straight, A-coded Description: Unshielded, Head A: female connector, M12, 4-pin, straight, unshielded, for power supply, for cable diameter 4 mm ... 6 mm Head B: - Connection systems: Screw-type terminals Permitted cross-section: ≤ 0.75 mm² 	DOS-1204-G	6007302

	Brief description	Type	Part no.
	<ul style="list-style-type: none"> • Connection type head A: Female connector, M12, 4-pin, straight, A-coded • Connection type head B: Male connector, M12, 4-pin, straight, A-coded • Signal type: Sensor/actuator cable • Cable: 2 m, 4-wire, PUR, halogen-free • Description: Sensor/actuator cable, unshielded • Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14-020UB3M2A14	2096000
	<ul style="list-style-type: none"> • Connection type head A: Female connector, M12, 4-pin, straight, A-coded • Connection type head B: Male connector, M12, 4-pin, straight, A-coded • Signal type: Sensor/actuator cable • Cable: 5 m, 4-wire, PUR, halogen-free • Description: Sensor/actuator cable, unshielded • Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14-050UB3M2A14	2096001
	<ul style="list-style-type: none"> • Connection type head A: Female connector, M12, 4-pin, straight, A-coded • Connection type head B: Male connector, M12, 4-pin, straight, A-coded • Signal type: Sensor/actuator cable • Cable: 10 m, 4-wire, PUR, halogen-free • Description: Sensor/actuator cable, unshielded • Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14-100UB3M2A14	2096002
	<ul style="list-style-type: none"> • Connection type head A: Female connector, M12, 4-pin, straight, A-coded • Connection type head B: Flying leads • Signal type: Sensor/actuator cable • Cable: 2 m, 4-wire, PUR, halogen-free • Description: Sensor/actuator cable, unshielded • Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14-020UB3XLEAX	2095607
	<ul style="list-style-type: none"> • Connection type head A: Female connector, M12, 4-pin, straight, A-coded • Connection type head B: Flying leads • Signal type: Sensor/actuator cable • Cable: 5 m, 4-wire, PUR, halogen-free • Description: Sensor/actuator cable, unshielded • Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14-050UB3XLEAX	2095608
	<ul style="list-style-type: none"> • Connection type head A: Female connector, M12, 4-pin, straight, A-coded • Connection type head B: Flying leads • Signal type: Sensor/actuator cable • Cable: 10 m, 4-wire, PUR, halogen-free • Description: Sensor/actuator cable, unshielded • Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14-100UB3XLEAX	2095609

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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