



# AHM36A-S9QC000A30

AHS/AHM36

**ABSOLUTE ENCODERS**

**SICK**  
Sensor Intelligence.



Illustration may differ



### Ordering information

Type	Part no.
AHM36A-S9QC000A30	1108595

Other models and accessories → [www.sick.com/AHS\\_AHM36](http://www.sick.com/AHS_AHM36)

### Detailed technical data

#### Performance

<b>Number of steps per revolution (max. resolution)</b>	16,384 (14 bit)
<b>Number of revolutions</b>	4,096 (12 bit)
<b>Max. resolution (number of steps per revolution x number of revolutions)</b>	14 bit x 12 bit (16,384 x 4,096)
<b>Error limits G</b>	0.35° (at 20 °C) <sup>1)</sup>
<b>Repeatability standard deviation <math>\sigma_r</math></b>	0.2° (at 20 °C) <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

<sup>2)</sup> In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

#### Interfaces

<b>Communication interface</b>	IO-Link
<b>Communication Interface detail</b>	IO-Link V1.1 / COM3 (230,4 kBaud)
<b>Initialization time</b>	2 s <sup>1)</sup>
<b>Cycle time</b>	≤ 3.2 ms
<b>Smart Sensor</b>	Efficient communication, Enhanced Sensing, diagnosis, Smart Task
<b>Process data</b>	Position, speed, electronic cams, limit values, linear position, linear speed, errors and warnings, switching signals on pin 2, Length, switching signals on pin 4
<b>Parameterising data</b>	Number of steps per revolution Number of revolutions PRESET Counting direction Sampling rate for speed calculation Unit for output of the speed value Round axis functionality Electronic cams(2 channels x 8 cams) Limit values Linear measuring length per 360° Pin 2 configuration

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> Between input signal on pin 2 and associated output signal on pin 4.

	Configuration of length measurement (IO-Link mode) Configuration of length monitoring (IO-Link and SIO mode) Configuration of trigger after a defined length (SIO mode)
<b>Available diagnostics data</b>	Minimum and maximum temperature Maximum speed Power-on counter Operating hours counter power-on/motion Counter of direction changes/number of movements cw/number of movements ccw Minimum and maximum operating voltage Distance covered Number of trigger signals on pin 2
<b>Status information</b>	Via status LED
<b>Switching input/Switching output</b>	✓
<b>Pin 2 input frequency</b>	≤ 100 Hz
<b>Output frequency pin 2</b>	≤ 100 Hz
<b>Output frequency pin 4</b>	≤ 100 Hz
<b>Latency</b>	3.5 ms <sup>2)</sup>

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> Between input signal on pin 2 and associated output signal on pin 4.

### Electrical data

<b>Connection type</b>	Male connector, M12, 4-pin, universal
<b>Supply voltage</b>	18 ... 30 V
<b>Power consumption</b>	≤ 1.5 W
<b>Reverse polarity protection</b>	✓
<b>MTTFd: mean time to dangerous failure</b>	240 years (EN ISO 13849-1) <sup>1)</sup>

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

### Mechanical data

<b>Mechanical design</b>	Solid shaft, Servo flange
<b>Shaft diameter</b>	8 mm
<b>Shaft length</b>	12 mm
<b>Weight</b>	0.12 kg <sup>1)</sup>
<b>Shaft material</b>	Stainless steel
<b>Flange material</b>	Aluminum
<b>Housing material</b>	Zinc
<b>Start up torque</b>	< 1 Ncm (+20 °C)
<b>Operating torque</b>	< 1 Ncm (+20 °C)
<b>Permissible shaft loading</b>	40 N (radial) 20 N (axial)
<b>Operating speed</b>	≤ 6,000 min <sup>-1</sup>
<b>Moment of inertia of the rotor</b>	2.5 gcm <sup>2</sup>
<b>Bearing lifetime</b>	3.6 x 10 <sup>8</sup> revolutions
<b>Angular acceleration</b>	≤ 500,000 rad/s <sup>2</sup>

<sup>1)</sup> Based on devices with male connector.

### Ambient data

<b>EMC</b>	According to EN 61000-6-2, EN 61000-6-3 and EN 61131-9
<b>Enclosure rating</b>	IP66 (IEC 60529) IP67 (IEC 60529)
<b>Permissible relative humidity</b>	90 % (Condensation not permitted)
<b>Operating temperature range</b>	-40 °C ... +85 °C
<b>Storage temperature range</b>	-40 °C ... +100 °C, without package
<b>Resistance to shocks</b>	100 g, 6 ms (EN 60068-2-27)
<b>Resistance to vibration</b>	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

### Smart Task

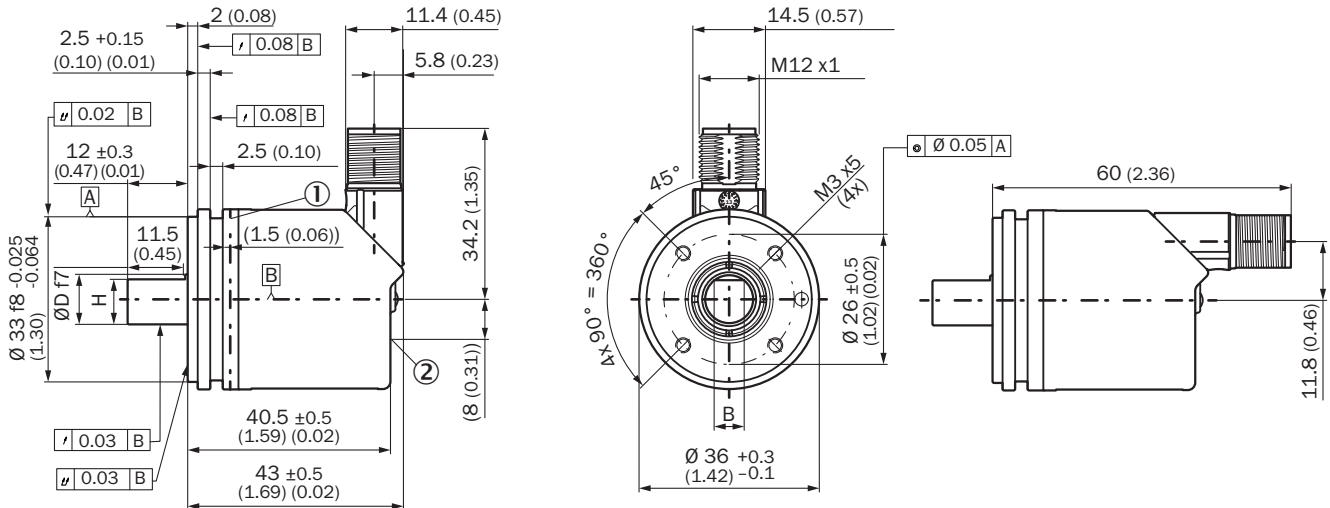
<b>Smart Task name</b>	Length measurement and trigger
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### Classifications

<b>ECLASS 5.0</b>	27270502
<b>ECLASS 5.1.4</b>	27270502
<b>ECLASS 6.0</b>	27270590
<b>ECLASS 6.2</b>	27270590
<b>ECLASS 7.0</b>	27270502
<b>ECLASS 8.0</b>	27270502
<b>ECLASS 8.1</b>	27270502
<b>ECLASS 9.0</b>	27270502
<b>ECLASS 10.0</b>	27270502
<b>ECLASS 11.0</b>	27270502
<b>ECLASS 12.0</b>	27270502
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

Dimensional drawing (Dimensions in mm (inch))

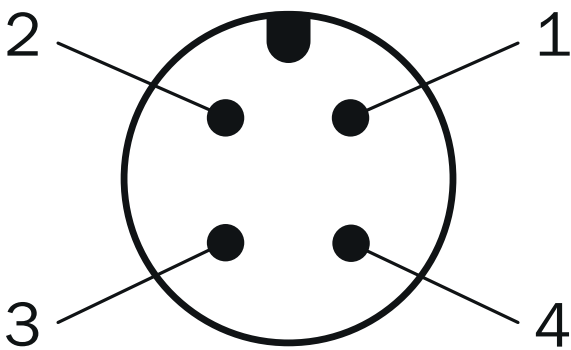
Solid shaft, servo flange, male connector



- ① Measuring point for operating temperature
- ② Measuring point for vibrations

Type	Shaft diameter $\varnothing D \text{ f7}$	B	H
AHx36x-S1xxxxxxxx AHx36x-S3xxxxxxxx	6 mm	3,6 mm	5,4 mm
AHx36x-S9xxxxxxxx AHx36x-S5xxxxxxxx	8 mm	3,9 mm	7,5 mm
AHx36x-S2xxxxxxxx AHx36x-S4xxxxxxxx AHx36x-SCxxxxxxxx	10 mm	6 mm	9 mm
AHx36x-SAxxxxxxxx AHx36x-S8xxxxxxxx	1/4"	3,85 mm	5,7 mm
AHx36x-SBxxxxxxxx AHx36x-S7xxxxxxxx	3/8"	4,35 mm	9 mm







PIN assignment







PIN	Wire color	Signal	Function		
			Basic	Advanced	Advanced Smart Task
1	Brown	L+	Encoder supply voltage 18-30 V (+Us)		
2	White	I/Q	Not connected - no function	Multifunctional pin (configurable as switching input or switching output)	
3	Blue	L-	Encoder supply voltage 0 V (GND)		
4	Black	C/Q	IO-Link communication		Switching output (SIO mode)
			-		

### Recommended accessories

Other models and accessories → [www.sick.com/AHS\\_AHM36](http://www.sick.com/AHS_AHM36)

	Brief description	Type	Part no.
<b>Shaft adaptation</b>			
	Double loop coupling, shaft diameter 8 mm / 10 mm, max. shaft offset: radially +/- 0,25 mm, axially +/-0,4 mm, angle +/- 4 degrees;max. speed 10.000 rpm, -30 to +120 degrees Celsius, torsional spring stiffness of 150 Nm/rad	KUP-0810-D	5326704
	Claw coupling, shaft diameter 8 mm / 10 mm, damping element 80 shore blue, maximum shaft offset: radial ± 0.22 mm, axial ± 1 mm angular ± 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, -30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0810-J	2128267
<b>Others</b>			
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Description:</b> Unshielded, Head A: female connector, M12, 4-pin, straight, unshielded, for power supply, for cable diameter 4 mm ... 6 mm Head B: -</li> <li>• <b>Connection systems:</b> Screw-type terminals</li> <li>• <b>Permitted cross-section:</b> ≤ 0.75 mm<sup>2</sup></li> </ul>	DOS-1204-G	6007302
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Connection type head B:</b> Male connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Signal type:</b> Sensor/actuator cable</li> <li>• <b>Cable:</b> 2 m, 4-wire, PUR, halogen-free</li> <li>• <b>Description:</b> Sensor/actuator cable, unshielded</li> <li>• <b>Application:</b> Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14-020UB3M2A14	2096000
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Connection type head B:</b> Male connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Signal type:</b> Sensor/actuator cable</li> <li>• <b>Cable:</b> 5 m, 4-wire, PUR, halogen-free</li> <li>• <b>Description:</b> Sensor/actuator cable, unshielded</li> <li>• <b>Application:</b> Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14-050UB3M2A14	2096001
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Connection type head B:</b> Male connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Signal type:</b> Sensor/actuator cable</li> <li>• <b>Cable:</b> 10 m, 4-wire, PUR, halogen-free</li> <li>• <b>Description:</b> Sensor/actuator cable, unshielded</li> <li>• <b>Application:</b> Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14-100UB3M2A14	2096002

	Brief description	Type	Part no.
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Connection type head B:</b> Flying leads</li> <li>• <b>Signal type:</b> Sensor/actuator cable</li> <li>• <b>Cable:</b> 2 m, 4-wire, PUR, halogen-free</li> <li>• <b>Description:</b> Sensor/actuator cable, unshielded</li> <li>• <b>Application:</b> Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14-020UB3XLEAX	2095607
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Connection type head B:</b> Flying leads</li> <li>• <b>Signal type:</b> Sensor/actuator cable</li> <li>• <b>Cable:</b> 5 m, 4-wire, PUR, halogen-free</li> <li>• <b>Description:</b> Sensor/actuator cable, unshielded</li> <li>• <b>Application:</b> Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14-050UB3XLEAX	2095608
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M12, 4-pin, straight, A-coded</li> <li>• <b>Connection type head B:</b> Flying leads</li> <li>• <b>Signal type:</b> Sensor/actuator cable</li> <li>• <b>Cable:</b> 10 m, 4-wire, PUR, halogen-free</li> <li>• <b>Description:</b> Sensor/actuator cable, unshielded</li> <li>• <b>Application:</b> Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14-100UB3XLEAX	2095609
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Male connector, M12, 4-pin, A-coded</li> <li>• <b>Connection type head B:</b> Female connector, M12, 4-pin, A-coded</li> <li>• <b>Connection type head C:</b> Female connector, M12, 4-pin, A-coded</li> <li>• <b>Signal type:</b> Sensor/actuator cable</li> <li>• <b>Cable:</b> 0.11 m, PVC</li> <li>• <b>Description:</b> Sensor/actuator cable, Y-Junction, 2 x female connector M12, 4-pin, straight, 0.11 m PVC-cable, 1 x male connector M12, 4-pin, straight, to connect SICK Sensors with SICK Smart Sensors</li> <li>• <b>Note:</b> T-coupler 2 x M12 female + M12 male straight with cable</li> </ul>	SYL-1204-G0M11-X1	6055011

## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

## WORLDWIDE PRESENCE:

Contacts and other locations –[www.sick.com](http://www.sick.com)