

AHS36A-S1QC016384

AHS/AHM36

ABSOLUTE ENCODERS





Ordering information

Туре	Part no.
AHS36A-S1QC016384	1101565

Other models and accessories → www.sick.com/AHS_AHM36

Illustration may differ



Detailed technical data

Performance

Number of steps per revolution (max. resolution)	16,384 (14 bit)
Error limits G	0.35° (at 20 °C) 1)
Repeatability standard deviation σ_{r}	0.2° (at 20 °C) ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

Interfaces

Communication interface	IO-Link
Communication Interface detail	IO-Link V1.1 / COM3 (230,4 kBaud)
Initialization time	2 s ¹⁾
Cycle time	≤ 3.2 ms
Smart Sensor	Efficient communication, Enhanced Sensing, diagnosis
Process data	Position, speed, electronic cams, limit values, linear position, linear speed, errors and warnings, switching signals on pin $\bf 2$
Parameterising data	Number of steps per revolution PRESET Counting direction Sampling rate for speed calculation Unit for output of the speed value Electronic cams(2 channels x 8 cams) Limit values Linear measuring length per 360° Pin 2 configuration
Available diagnostics data	Minimum and maximum temperature Maximumspeed Power-on counter Operatinghours counter power-on/motion Counter of direction changes/number of movements cw/number of movements ccw Minimum andmaximum operating voltage Distance covered

 $^{^{1)}\,\}mathrm{Valid}$ positional data can be read once this time has elapsed.

 $^{^{2)}}$ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Status information	Via status LED
Switching input/Switching output	√
Pin 2 input frequency	≤ 100 Hz
Output frequency pin 2	≤ 100 Hz

 $^{^{1)}\,\}mathrm{Valid}$ positional data can be read once this time has elapsed.

Electrical data

Connection type	Male connector, M12, 4-pin, universal
Supply voltage	18 30 V
Power consumption	≤ 1.5 W
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	240 years (EN ISO 13849-1) 1)

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532

Mechanical data

Mechanical design	Solid shaft, Servo flange
Shaft diameter	6 mm
Shaft length	12 mm
Weight	$0.12 \text{kg}^{ 1)}$
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Zinc
Start up torque	< 1 Ncm (+20 °C)
Operating torque	< 1 Ncm (+20 °C)
Permissible shaft loading	40 N (radial) 20 N (axial)
Operating speed	≤ 6,000 min ⁻¹
Moment of inertia of the rotor	2.5 gcm ²
Bearing lifetime	3.6 x 10^8 revolutions
Angular acceleration	$\leq 500,000 \text{ rad/s}^2$

 $^{^{1)}}$ Based on devices with male connector.

Ambient data

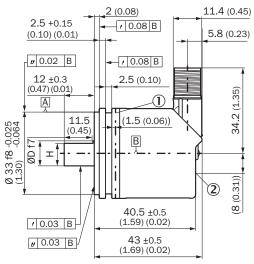
EMC	According to EN 61000-6-2, EN 61000-6-3 and EN 61131-9
Enclosure rating	IP66 (IEC 60529) IP67 (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +85 °C
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)

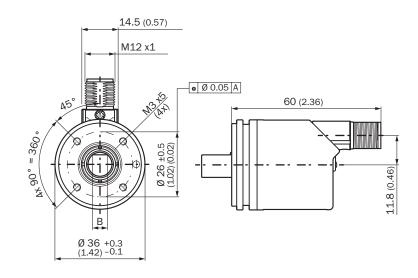
Classifications

ECLASS 5.0	27270502
ECLASS 5.1.4	27270502
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270502
ECLASS 8.0	27270502
ECLASS 8.1	27270502
ECLASS 9.0	27270502
ECLASS 10.0	27270502
ECLASS 11.0	27270502
ECLASS 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Solid shaft, servo flange, male connector



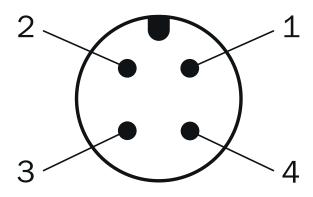


- ① Measuring point for operating temperature
- Measuring point for vibrations

Туре	Shaft diameter Ø D f7	В	Н
AHx36x-S1xxxxxxxx AHx36x-S3xxxxxxxx	6 mm	3,6 mm	5,4 mm
AHx36x-S9xxxxxxxx AHx36x-S5xxxxxxxx	8 mm	3,9 mm	7,5 mm
AHx36x-S2xxxxxxx AHx36x-S4xxxxxxxx	10 mm	6 mm	9 mm

Туре	Shaft diameter Ø D f7	В	Н
AHx36x-SCxxxxxxxx			
AHx36x-SAxxxxxxx AHx36x-S8xxxxxxxx	1/4"	3,85 mm	5,7 mm
AHx36x-SBxxxxxxxx AHx36x-S7xxxxxxxx	3/8"	4,35 mm	9 mm

PIN assignment



PIN	Wire color	Signal	Function		
			Basic	Advanced	Advanced Smart Task
1	Brown	L+	Encoder supply voltage	ge 18-30 V (+Us)	
2	White	I/Q	Not connected - no function	Multifunctional pin (configurable as switching input or switching output)	
3	Blue	Ŀ	Encoder supply voltage 0 V (GND)		
4	Black	C/Q	IO-Link communication		
			-		Switching output (SIO mode)

Recommended accessories

Other models and accessories → www.sick.com/AHS_AHM36

	Brief description	Туре	Part no.
Other mounting	ng accessories		
	Measuring wheel with O-ring (NBR70) for 6 mm solid shaft, circumference 300 mm	BEF-MR006030R	2055634
	O-ring for measuring wheels (circumference 200 mm)	BEF-OR-053-040	2064061
	O-ring for measuring wheels (circumference 300 mm), 2x O-ring	BEF-OR-083-050	2064076

	Brief description	Туре	Part no.
Shaft adaptat	ion		
	Bellows coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial \pm 0.25 mm, axial \pm 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0606-B	5312981
	Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial \pm 0.25 mm, axial \pm 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0610-B	5312982
10	Double loop coupling, shaft diameter 6 mm $\!\!/$ 10 mm, max. shaft offset: radially +/- 2,5 mm, axially +/- 3 mm, angle +/- 10 degrees;max. speed 3.000 rpm, -30 to +80 degrees Celsius, torsional spring stiffness of 25 Nm/rad	KUP-0610-D	5326697
(i	Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial +/- 0.3 mm, axial +/- 0.4 mm, angular +/- 2.5°; max. speed 12,000 rpm, -10° to +80°C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin	KUP-0610-F	5312985
	Claw coupling, shaft diameter 6 mm $/$ 10 mm, damping element 80 shore blue, maximum shaft offset: radial \pm 0.22 mm, axial \pm 1 mm angular \pm 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, –30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0610-J	2127056
Others			
	Connection type head A: Female connector, M12, 4-pin, straight, A-coded Description: Unshielded, Head A: female connector, M12, 4-pin, straight, unshielded, for power supply, for cable diameter 4 mm 6 mm Head B: - Connection systems: Screw-type terminals Permitted cross-section: ≤ 0.75 mm²	DOS-1204-G	6007302
66	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Male connector, M12, 4-pin, straight, A-coded Signal type: Sensor/actuator cable Cable: 2 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 020UB3M2A14	2096000
66	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Male connector, M12, 4-pin, straight, A-coded Signal type: Sensor/actuator cable Cable: 5 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 050UB3M2A14	2096001
66	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Male connector, M12, 4-pin, straight, A-coded Signal type: Sensor/actuator cable Cable: 10 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 100UB3M2A14	2096002
No.	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Flying leads Signal type: Sensor/actuator cable Cable: 2 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 020UB3XLEAX	2095607
No.	 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Flying leads Signal type: Sensor/actuator cable Cable: 5 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 050UB3XLEAX	2095608

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 Connection type head A: Female connector, M12, 4-pin, straight, A-coded Connection type head B: Flying leads Signal type: Sensor/actuator cable Cable: 10 m, 4-wire, PUR, halogen-free Description: Sensor/actuator cable, unshielded Application: Zones with oils and lubricants, Drag chain operation, Robot 	YF2A14- 100UB3XLEAX	2095609

SICK AT A GLANCE

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