



DBS36E-S3AZ0S115

DBS36/50

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	Part no.
DBS36E-S3AZ0S115	1128665

Other models and accessories → www.sick.com/DBS36_50

Detailed technical data

Features

Special device	✓
Specialty	Customized solid shaft, Diameter 5 mm, length 12.5 mm Customized face mount flange (clamp collar diameter 16 mm, 3*M3 on hole circle diameter 20 mm) Cable, with male connector, M12, 0.3 m, angled Customer-specific pin assignment IPEK part no.: 375-0222-00
Standard reference device	DBS36E-S3AK00200, 1063728

Safety-related parameters

MTTF_D (mean time to dangerous failure)	600 years (EN ISO 13849-1) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	200
Measuring step	90°, electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	± 54° / pulses per revolution
Duty cycle	≤ 0.5 ± 5 %

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / RS-422
Number of signal channels	6-channel
Initialization time	< 3 ms
Output frequency	≤ 300 kHz
Load current	≤ 30 mA
Operating current	≤ 50 mA (without load)

Electrical data

Connection type	Special design
Connection type Detail	Cable, with male connector, M12, 0.3 m, angled

¹⁾ The short-circuit rating is only given if Us and GND are connected correctly.

Supply voltage	4.5 ... 5.5 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Short-circuit protection of the outputs	✓ ¹⁾

¹⁾ The short-circuit rating is only given if Us and GND are connected correctly.

Mechanical data

Mechanical design	Special design
Mechanical type detail	Solid shaft, face mount flange, 5 mm x 12.5 mm
Shaft diameter	With face
Weight	+ 150 g (with connecting cable)
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Material, cable	PVC
Start up torque	+ 0.5 Ncm (+20 °C)
Operating torque	0.4 Ncm (+20 °C)
Permissible movement static	¹⁾
Permissible movement dynamic	¹⁾
Permissible shaft loading	40 N (radial) ¹⁾ 20 N (axial)
Operating speed	6,000 min ⁻¹ ²⁾
Maximum operating speed	≤ 8,000 min ⁻¹ ³⁾
Moment of inertia of the rotor	0.6 gcm ²
Bearing lifetime	2 x 10 ⁹ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Higher values are possible using limited bearing life.

²⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

³⁾ No permanent operation. Decreasing signal quality.

Ambient data

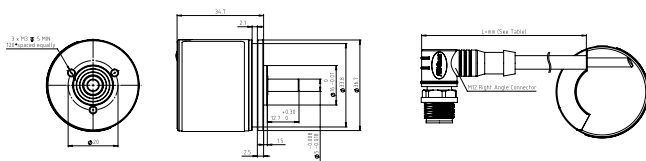
EMC	According to EN 61000-6-2 and EN 61000-6-3 (class A)
Enclosure rating	IP65
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-20 °C ... +85 °C, -35 °C ... +95 °C on request
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590

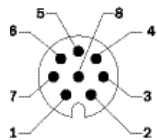
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))



PIN assignment

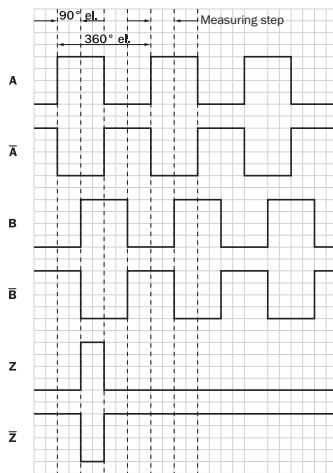
View of M12 device connector on cable/housing



Pin, 8-pin, male connector M12	Signal TTL, HTL	Explanation
1	GND	Ground connection of the encoder
2	+U _s	Supply voltage
3	A	Signal line
4	B	Signal line
5	Z	Signal line
6	A	Signal line
7	B	Signal line
8	Screen	Screen
-	Not connected	Not connected
-	Not connected	Not connected
-	Not connected	Not connected
-	Not connected	Not connected
Screen	Screen	Screen connecte to encoder housing

Diagrams

Signal outputs for electrical interfaces TTL and HTL




Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

① Interfaces G, P, R only for channels A, B, Z.

Supply voltage	Output
4.5 V...5.5 V	TTL/RS422
7 V...30 V	TTL/RS422
7 V...30 V	HTL/Push Pull
7 V...27 V	HTL/push pull, 3 channel
4.5 V...5.5 V	Open Collector NPN, 3 channel
4.5 V...30 V	Open Collector NPN, 3 channel

Recommended accessories

Other models and accessories → www.sick.com/DBS36_50

	Brief description	Type	Part no.
Shaft adaptation			
	Claw coupling, shaft diameter 6 mm / 10 mm, damping element 80 shore blue, maximum shaft offset: radial ± 0.22 mm, axial ± 1 mm angular ± 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, -30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0610-J	2127056

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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