

DBS60E-B5EP00S22

DBS60

INCREMENTAL ENCODERS





Ordering information

Туре	Part no.
DBS60E-B5EP00S22	1074405

Other models and accessories → www.sick.com/DBS60





Detailed technical data

Features

Special device	J.
Specialty	Cable 8-core, universal 1.0 m with male connector M12 with panel mounting
Standard reference device	DBS60E-B5EP01024,1092140

Performance

Pulses per revolution	1,024
Measuring step	≤ 90°, electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	6-channel
Initialization time	< 5 ms ¹⁾
Output frequency	+ 300 kHz ²⁾
Load current	≤ 30 mA, per channel
Power consumption	≤ 1 W (without load)

 $^{^{1)}}$ Valid signals can be read once this time has elapsed.

Electrical data

Connection type	Cable, 8-wire, with male connector, M12, 8-pin, universal, 0.5 m $^{1)}$
Supply voltage	10 27 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

 $^{^{2)}}$ Up to 450 kHz on request.

 $^{^{2)}\,\}mbox{Short-circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ²⁾
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) 3)

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	12 mm Shaft isolated
Flange type / stator coupling	2-sided stator coupling, slot, screw hole circle 63–83 mm
Weight	+ 0.25 kg ¹⁾
Shaft material	Stainless steel with plastic shaft
Flange material	Aluminum
Housing material	Aluminum
Material, cable	PVC
Start up torque	+ 0.5 Ncm (+20 °C)
Operating torque	0.4 Ncm (+20 °C)
Permissible movement static	\pm 0.3 mm (radial) \pm 0.5 mm (axial) $^{2)}$
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) $^{2)}$
Operating speed	6,000 min ^{-1 3)}
Maximum operating speed	9,000 min ⁻¹ ⁴⁾
Moment of inertia of the rotor	50 gcm ²
Bearing lifetime	3.6 x 10 ⁹ revolutions
Angular acceleration	≤ 200,000 rad/s²

¹⁾ Based on encoder with male connector or cable with male connector.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-20 °C +85 °C ²⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	200 g, 3 ms (EN 60068-2-27)

¹⁾ With mating connector fitted.

 $^{^{2)}\,\}mathrm{Short\text{-}circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $^{^{2)}\,\}mathrm{Not}$ apllicable for stator coupling type C and K.

 $^{^{3)}}$ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

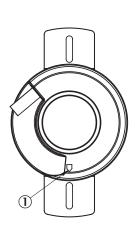
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)
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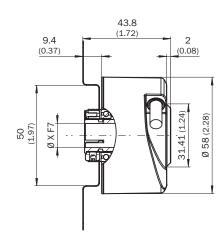
 $^{^{1)}}$ With mating connector fitted.

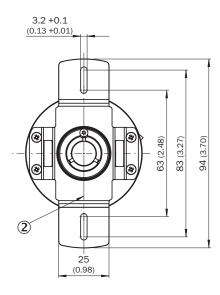
Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))







- XF7 values see shaft diameter table for blind hollow shaft
- ① Zero pulse mark on housing
- ② Zero pulse mark on flange under stator coupling

Type Blind hollow shaft	Shaft diameter XF7
DBS60x-BAxxxxxxxx	6 mm

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

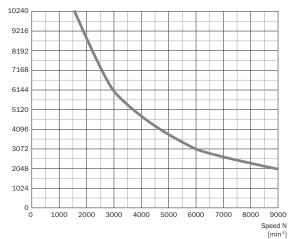
Type Blind hollow shaft	Shaft diameter XF7
DBS60x-B1xxxxxxxxx	
DBS60x-BBxxxxxxxx DBS60x-B2xxxxxxxxx	8 mm
DBS60x-BCxxxxxxxx DBS60x-B3xxxxxxxxx	3/8"
DBS60x-BDxxxxxxxx DBS60x-B4xxxxxxxx	10 mm
DBS60x-BExxxxxxxx DBS60x-B5xxxxxxxxx	12 mm
DBS60x-BFxxxxxxxx DBS60x-B6xxxxxxxxx	1/2"
DBS60x-BGxxxxxxxx DBS60x-B7xxxxxxxxx	14 mm
DBS60x-BHxxxxxxxxx DBS60x-B8xxxxxxxxx	15 mm
DBS60x-BJxxxxxxxx	5/8"

PIN assignment

PIN	Signal TTL/HTL	Beschreibung
1	Α	Signalleitung
2	A	Signalleitung
3	B	Signalleitung
4	В	Signalleitung
5	Z	Signalleitung
6	Z	Signalleitung
7	GND	Masseanschluss des Encoders
8	+Us	Versorgungsspannung (potentialfrei zum Gehäuse)
Schirm	Schirm	Schirm encoderseitig mit Steckergehäuse
		verbunden. Steuerungsseitig mit Erde verbinden.

Diagrams





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