

DBS60E-REFCZS176

DBS60

INCREMENTAL ENCODERS



Ordering information

Туре	Part no.
DBS60E-REFCZS176	1131435

Other models and accessories → www.sick.com/DBS60



Detailed technical data

Features

Special device	✓
Specialty	512 pulses per revolution Through hollow shaft clamping at the back 12 mm Customized encoder flange Customer-specific pin assignment
Standard reference device	DBS60E-T4FCC1024, 1111610

Performance

Pulses per revolution	512
Measuring step	≤ 90°, electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL/HTL ¹⁾
Number of signal channels	6-channel
Initialization time	< 5 ms ²⁾
Output frequency	+ 300 kHz ³⁾
Load current	≤ 30 mA, per channel
Power consumption	≤ 0.5 W (without load)

¹⁾ Output level depends on the supply voltage.

Electrical data

Connection type	Male connector, M12, 8-pin, radial, Customer-specific pin assignment
Supply voltage	4.5 30 V
Reference signal, number	1

 $^{^{1)}}$ Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

 $^{^{\}rm 2)}\,{\rm Valid}$ signals can be read once this time has elapsed.

 $^{^{3)}}$ Up to 450 kHz on request.

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	√
Short-circuit protection of the outputs	✓ ¹⁾
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) ²⁾

 $^{^{1)}}$ Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

Mechanical data

Mechanical design	Through hollow shaft, rear clamping
Shaft diameter	12 mm
Flange type / stator coupling	Customer-specific flange
Weight	+ 0.25 kg ¹⁾
Shaft material	Stainless steel with plastic shaft
Flange material	Aluminum
Housing material	Aluminum
Start up torque	+ 0.5 Ncm (+20 °C)
Operating torque	0.4 Ncm (+20 °C)
Permissible movement static	\pm 0.3 mm (radial) \pm 0.5 mm (axial) ²⁾
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) ²⁾
Operating speed	6,000 min ^{-1 3)}
Maximum operating speed	9,000 min ⁻¹ ⁴⁾
Moment of inertia of the rotor	50 gcm ²
Bearing lifetime	3.6 x 10 ⁹ revolutions
Angular acceleration	≤ 200,000 rad/s²

¹⁾ Based on encoder with male connector or cable with male connector.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-30 °C +100 °C, at maximum 3,000 pulses per revolution ²⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	200 g, 3 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

¹⁾ With mating connector fitted.

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 $^{^{2)}\,\}mathrm{Not}$ apllicable for stator coupling type C and K.

 $^{^{3)}}$ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

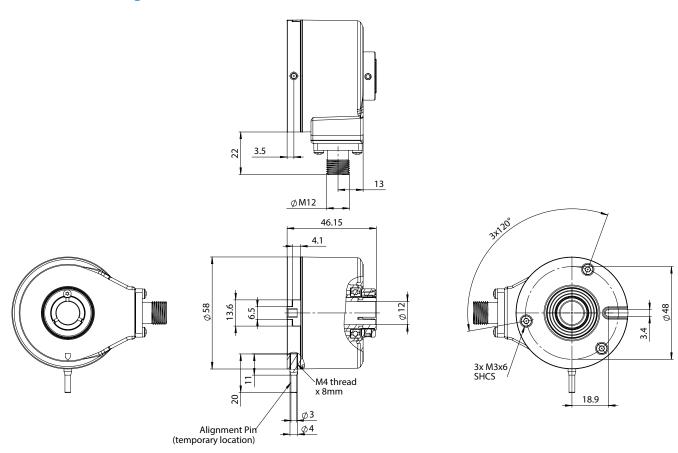
⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))



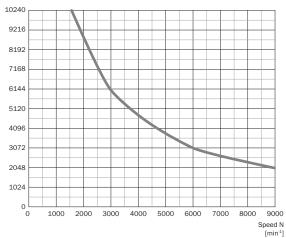
PIN assignment



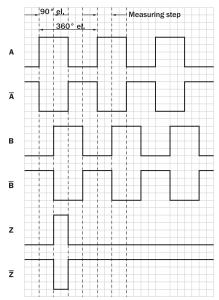
Male connector M12, 8-pin	TTL/HTL 6-channel signal	Explanation
1	GND	Ground connection
2	Us	Supply Voltage
3	A	Signal wire
4	A-	Signal wire
5	В	Signal wire
6	B-	Signal wire
7	Z	Signal wire
8	Z-	Signal wire
Screen	Screen	Screen connected to Encoder housing

Diagrams

Pulses per revolution



Signal outputs for electrical interfaces TTL and HTL

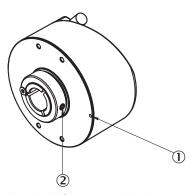


Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V 5,5 V	ΠL
10 V 30 V	ΠL
10 V 27 V	HTL
4,5 V 30 V	TTL/HTL universal
4,5 V 30 V	ΠL

Operation note

Hollow shaft



Attention! If stator coupling is mounted, the zero pulse mark can be hidden by the stator coupling

- ① Zero pulse mark on flange
- ② Zero pulse is active when screw of clamping is inline with zero pulse mark on flange or housing mark

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