

DBS60E-T8ECBS127

DBS60

INCREMENTAL ENCODERS



Illustration may differ

Ordering information

Туре	Part no.	
DBS60E-T8ECBS127	1110195	

Other models and accessories → www.sick.com/DBS60



Detailed technical data

Features

Special device	√
Specialty	Item DBS60E-T8ECB0S127 is based on two encoders of type DBS60E-T8ECB05000 with customized pin allocation, which are mechanically connected via an adapter The following technical data is valid for the set of 2 Encoders: Mass: 0.55 kg, Start up torque: 1.0 Ncm (+20°C), Operating torque: 0.8 Ncm (+20°C), moment of inertia of the rotor: 100 gcm²
Standard reference device	DBS60E-T8ECB05000

Performance

Pulses per revolution	2,500
Measuring step	≤ 90°, electric/pulses per revolution
Measuring step deviation	± 36° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 10 %

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	6-channel
Initialization time	< 5 ms ¹⁾
Output frequency	+ 300 kHz ²⁾
Load current	≤ 30 mA, per channel
Power consumption	≤ 1 W (without load)

 $^{^{1)}}$ Valid signals can be read once this time has elapsed.

Electrical data

Connection type	Male connector, M12, 8-pin, radial
Supply voltage	10 27 V
Reference signal, number	1

 $^{^{1)}\,\}mbox{Short-circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

 $^{^{2)}}$ Up to 450 kHz on request.

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reference signal, position	90°, electric, logically gated with A and B	
Reverse polarity protection	✓	
Short-circuit protection of the outputs	✓ ¹⁾	
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) ²⁾	

 $^{^{1)}}$ Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

Mechanical data

Mechanical design	Through hollow shaft, Front clamp
Shaft diameter	15 mm Shaft isolated
Flange type / stator coupling	Stator coupling, 2-sided, screw hole circle 63 mm
Weight	+ 0.55 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Start up torque	+ 1 Ncm (+20 °C)
Operating torque	0.8 Ncm (+20 °C)
Permissible movement static	\pm 0.3 mm (radial) \pm 0.5 mm (axial) $^{2)}$
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) ²⁾
Operating speed	6,000 min ^{-1 3)}
Maximum operating speed	9,000 min ⁻¹ ⁴⁾
Moment of inertia of the rotor	100 gcm ²
Bearing lifetime	3.6 x 10 ⁹ revolutions
Angular acceleration	≤ 200,000 rad/s²

 $^{^{1)}\,\}mathrm{Based}$ on encoder with male connector or cable with male connector.

Ambient data

ЕМС	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-20 °C +85 °C ²⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	200 g, 3 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $^{^{1)}}$ With mating connector fitted.

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 $^{^{\}rm 2)}$ Not apllicable for stator coupling type C and K.

 $^{^{}m 3)}$ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

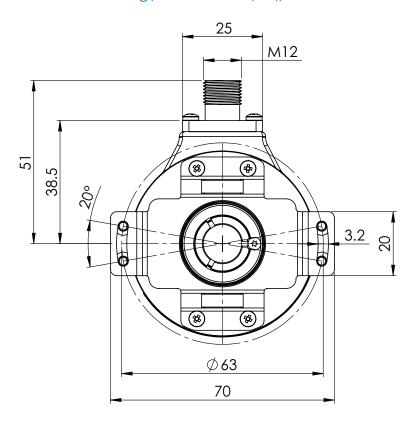
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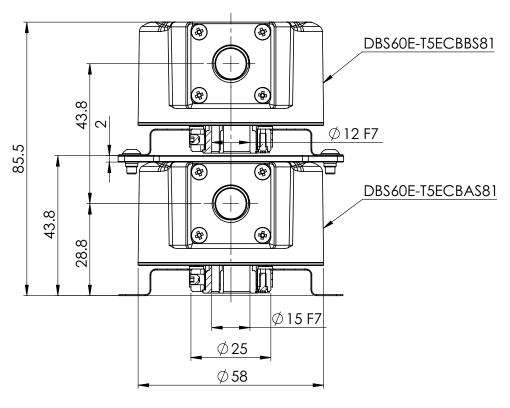
INCREMENTAL ENCODERS

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))





Attachment specifications



Additional installation instruction:
Step 1: Mount the encoder (A) in the preferred position
Step 2: Followed by the encoder (B)
Step 3: Connect encoder A and B by tightening the four screws

PIN assignment

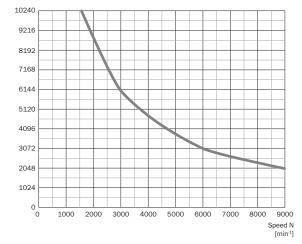




Pin, 8-pin, M12		
connector	TTI/HTL signal	Explanation
1	'В	Signal cable
2	Z	Signal cable
3	В	Signal cable
4	A	Signal cable
	· A	Signal cable
6	. Z	Signal cable
7	GND	Ground connection of the encoder
8	+U _S	Supply voltage (volt-free to housing)
Shield	Shield	Shield connected to housing on side of encoder. Connected to ground on side of control.

Diagrams

Pulses per revolution



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