

DBS60E-TBZZ00S31

DBS60

INCREMENTAL ENCODERS



Illustration may differ

Ordering information

Туре	Part no.
DBS60E-TBZZ00S31	1078428

Other models and accessories → www.sick.com/DBS60



Detailed technical data

Features

Special device	✓	
Specialty	Customized pcb with 10 zero pulse positions Cable, 8-wire, universal, 6 m with USB connector, A-code, customized pin allocation	
Standard reference device	DBS60E-TBEK01000, 1072396	

Performance

Pulses per revolution	640	
Measuring step	≤ 90°, electric/pulses per revolution	
Measuring step deviation	± 18° / pulses per revolution	
Error limits	Measuring step deviation x 3	
Duty cycle	≤ 0.5 ± 5 %	

Interfaces

Communication interface	Incremental	
Communication Interface detail	HTL / Push pull	
Number of signal channels	6-channel	
Initialization time	< 5 ms ¹⁾	
Output frequency	+ 300 kHz ²⁾	
Load current	≤ 30 mA, per channel	
Power consumption	≤ 1 W (without load)	

 $^{^{1)}}$ Valid signals can be read once this time has elapsed.

Electrical data

Connection type	Cable, 8-wire, with USB port, universal, 6 m, A-coded, Customer-specific pin assignment ¹⁾
Supply voltage	10 27 V
Reference signal, number	1
Reference signal, position	180°, electric, logically gated with A and B
Reverse polarity protection	✓

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

 $^{^{2)}}$ Up to 450 kHz on request.

 $^{^{2)}\,\}mbox{Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.$

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Short-circuit protection of the outputs	√ ²⁾
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) ³⁾

 $^{^{1)}}$ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

Mechanical data

Mechanical design	Through hollow shaft, Front clamp	
Shaft diameter	8 mm	
Flange type / stator coupling	2-sided stator coupling, slot, screw hole circle 63–83 mm	
Weight	+ 0.25 kg ¹⁾	
Shaft material	Stainless steel	
Flange material	Aluminum	
Housing material	Aluminum	
Material, cable	PVC	
Start up torque	+ 0.5 Ncm (+20 °C)	
Operating torque	0.4 Ncm (+20 °C)	
Permissible movement static	\pm 0.3 mm (radial) \pm 0.5 mm (axial) ²⁾	
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) ²⁾	
Operating speed	6,000 min ^{-1 3)}	
Maximum operating speed	9,000 min ^{-1 4)}	
Moment of inertia of the rotor	50 gcm ²	
Bearing lifetime	3.6 x 10 ⁹ revolutions	
Angular acceleration	$\leq 500,000 \text{ rad/s}^2$	

 $^{^{1)}}$ Based on encoder with male connector or cable with male connector.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3	
Enclosure rating	IP65, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)	
Permissible relative humidity	90 % (Condensation not permitted)	
Operating temperature range	-20 °C +85 °C ²⁾	
Storage temperature range	-40 °C +100 °C, without package	
Resistance to shocks	250 g, 3 ms (EN 60068-2-27)	
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)	

 $^{^{1)}}$ With mating connector fitted.

 $^{^{2)}\,\}mbox{Short-circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $^{^{2)}\,\}mathrm{Not}$ apllicable for stator coupling type C and K.

 $^{^{3)}}$ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

DBS60E-TBZZ00S31 | DBS60

INCREMENTAL ENCODERS

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

PIN assignment

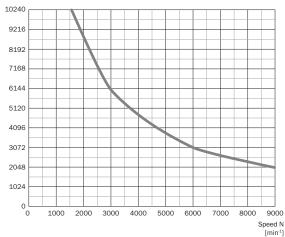




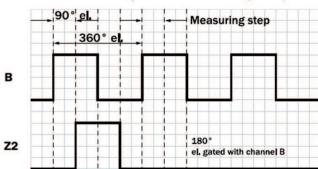
USB connector	TTI/HTL signal	Explanation
1	+U _S	Supply voltage (volt-free to housing)
2	В	Signal cable
3	Z	Signal cable
4	GND	Ground connection of the encoder
		Shield connected to housing on side
		of encoder. Connected to ground on
Shield	Shield	side of control.

Diagrams

Pulses per revolution



Width of the zero pulse in relation to a pulse period.



SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

WORLDWIDE PRESENCE:

Contacts and other locations -www.sick.com

