DBS60E-TEEPZOSO2 DBS60

INCREMENTAL ENCODERS



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Illustration may differ

Ordering information

Туре	Part no.
DBS60E-TEEPZ0S02	1132207

Other models and accessories -> www.sick.com/DBS60

CE

Detailed technical data

Special device I Specialty Communication interface HTL/Push pull, 3-channels 1-armed flat stator coupling, slot width 6 mm Temperature range: 0peration: 20480°C) Extended voltage range: 2730 VDC (Tmax. +80°C) Extended voltage range: 2730 VDC (Tmax. +60°C) Cable, PUR, Ø 5.5 mm, with male connector, M12, 4-pin, A-coded, shielded, 1.6 m Pulses per revolution: 1024 Package: single encoder in a plastic bag, the encoders with plastic bags are put into a bulk packaging Standard reference device DBS60E-TEEPD0048 Performance 1.024 Measuring step 90°, electric/pulses per revolution Measuring step deviation ±18° / pulses per revolution Error limits Measuring step deviation x 3 Duty cycle <0.5 ± 5 % Interfaces Incremental
1-armed flat stator coupling, slot width 6 mm Temperature range: Operation: -20+80°C, Storage: -30+85°C Voltage range: 10 27 VDC (Tmax. +80°C) Extended voltage range: > 27 30 VDC (Tmax. +60°C) Cable, PUR, Ø 5.5 mm, with male connector, M12, 4-pin, A-coded, shielded, 1.6 m Pulses per revolution: 1024 Package: single encoder in a plastic bag, the encoders with plastic bags are put into a bulk packagingStandard reference deviceDBS60E-TEEPD0048Performance1,024Pulses per revolution1,024Measuring step≤ 90°, electric/pulses per revolutionMeasuring step deviation± 18° / pulses per revolutionError limitsMeasuring step deviation x 3Duty cycle≤ 0.5 ± 5 %
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Duty cycle ≤ 0.5 ± 5 % Interfaces
Interfaces
Communication interface Incremental
Communication Interface detail HTL / Push pull
Number of signal channels 3 channel
Initialization time < 5 ms ⁻¹⁾
Output frequency + 300 kHz ²⁾
Load current ≤ 30 mA, per channel
Power consumption ≤ 1 W (without load)

 $^{\mbox{1}\mbox{}}$ Valid signals can be read once this time has elapsed.

 $^{2)}\,\rm Up$ to 450 kHz on request.

Electrical data

 $^{1)}$ Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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Supply voltage	10 27 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ¹⁾
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) ²⁾

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Mechanical data

Flange type / stator coupling	1-armed flat stator coupling, slot width 6 mm
Weight	+ 0.25 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Material, cable	PVC
Start up torque	+ 0.5 Ncm (+20 °C)
Operating torque	0.4 Ncm (+20 °C)
Permissible movement static	\pm 0.3 mm (radial) \pm 0.5 mm (axial) ²⁾
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) ²⁾
Operating speed	6,000 min ^{-1 3)}
Maximum operating speed	9,000 min ^{-1 4)}
Moment of inertia of the rotor	50 gcm ²
Bearing lifetime	3.6 x 10 ⁹ revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{1)}$ Based on encoder with male connector or cable with male connector.

 $^{2)}$ Not apllicable for stator coupling type C and K.

 $^{\rm 3)}$ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-20 °C +80 °C ²⁾
Storage temperature range	-30 °C +85 °C, without package
Resistance to shocks	250 g, 3 ms (EN 60068-2-27)

¹⁾ With mating connector fitted.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

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Resistance to vibration

30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

¹⁾ With mating connector fitted.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

 Image: 4 x M2,5; 5mm deep Customer Lage

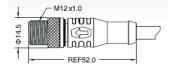
 Image: 4 x M2,5; 5mm deep Customer Lage

Dimensional drawing (Dimensions in mm (inch))

PIN assignment

PIN	Signal HTL	Explanation
1	+Us	Supply voltage
2	А	Signal line
3	GND	Ground connection of the encoder
4	В	Signal line
Thread	Shield	Connected to Encoder housing



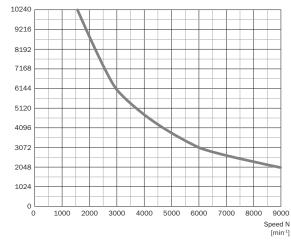


M12 Connector insert, A-coded

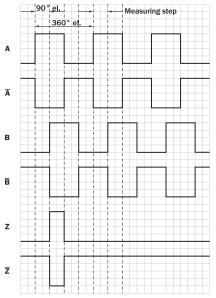
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Diagrams

Pulses per revolution



Signal outputs for electrical interfaces TTL and HTL



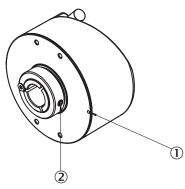
Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

-			
Sup	plv	vol	tage

Supply voltage	Output
4,5 V 5,5 V	TTL
10 V 30 V	TTL
10 V 27 V	HTL
4,5 V 30 V	TTL/HTL universal
4,5 V 30 V	TTL

Operation note

Hollow shaft



Attention! If stator coupling is mounted, the zero pulse mark can be hidden by the stator coupling

① Zero pulse mark on flange

② Zero pulse is active when screw of clamping is inline with zero pulse mark on flange or housing mark

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