Product data sheet

DFS60B-S1EZ00S02

DFS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.

Illustration may differ

Ordering information

Type	Part no.
DFS60B-S1EZ00S02	1104944

Other models and accessories ➜ www.sick.com/DFS60

Detailed technical data

Features

Special device	✓
Specialty	Number of lines 10,000 Male connector, M23 (6027537), 12-pin on cable end
Standard reference device	DFS60B-S1EK10000, 1056192

Safety-related parameters

$MTTF_D$ (mean time to dangerous failure)	300 years (EN ISO 13849-1) [1]

[1] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	10,000 [1]
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°

[1] See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	6-channel
Initialization time	40 ms
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.5 W (without load)

Electronics

Connection type	Special version
Connection type Detail	Male connector, M23 (6027537), 12-pin on cable end
Supply voltage	10 ... 32 V
Reference signal, number	1

[1] Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ [1]

[1] Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

Mechanics

Mechanical design	Solid shaft, Servo flange
Shaft diameter	6 mm With face
Shaft length	10 mm
Weight	+ 0.3 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.5 Ncm (+20 °C)
Operating torque	0.3 Ncm (+20 °C)
Permissible shaft loading	80 N (radial) 40 N (axial)
Operating speed	≤ 9,000 min^{-1} [1]
Moment of inertia of the rotor	6.2 gcm^2
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s^2

[1] Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-4
Enclosure rating	IP67, Housing side, male connector (IEC 60529) [1] IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	–40 °C ... +100 °C [2] –30 °C ... +100 °C [3]
Storage temperature range	–40 °C ... +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

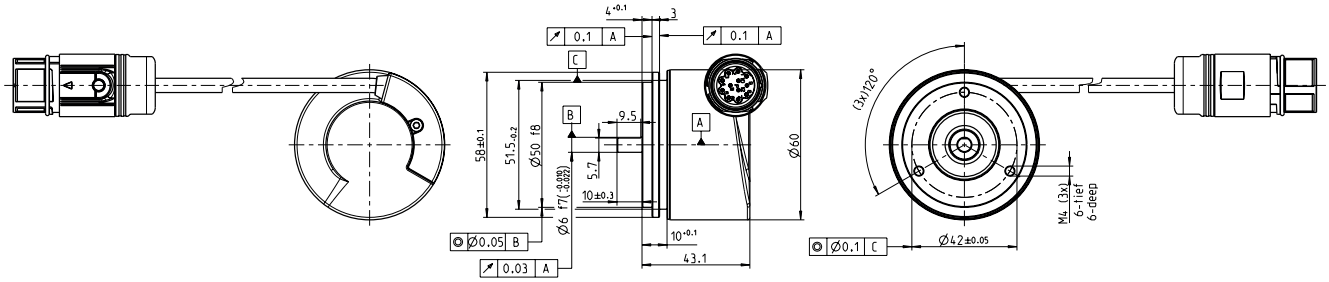
[1] With mating connector fitted.
[2] Stationary position of the cable.
[3] Flexible position of the cable.

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501

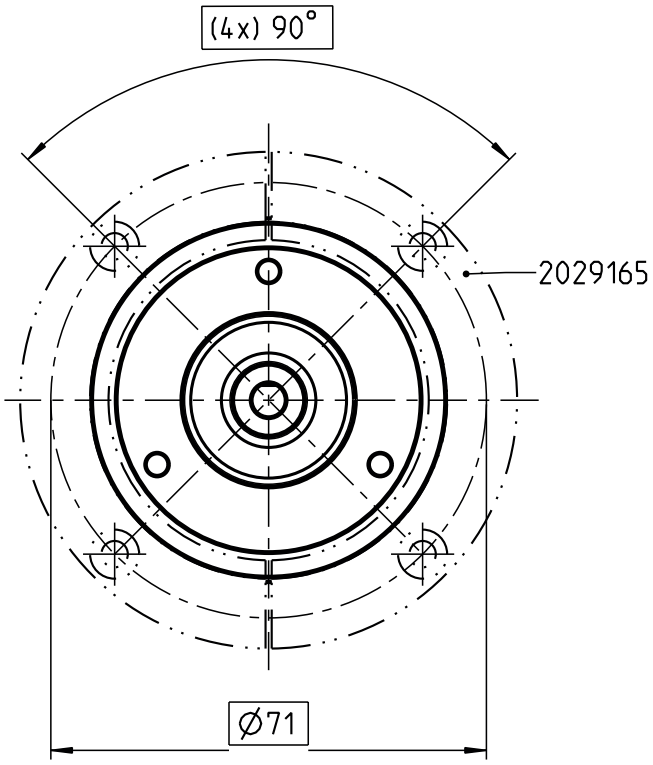
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

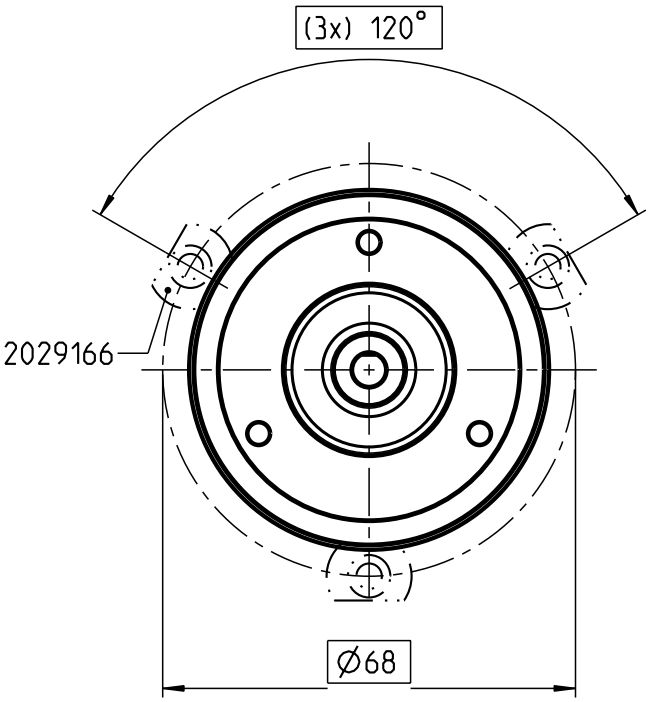


Attachment specifications

Mounting requirements for half-shell servo clamp



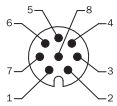
Mounting requirements for small servo clamp



PIN assignment

Cable, 8-wire

View of M12 male device connector on encoder



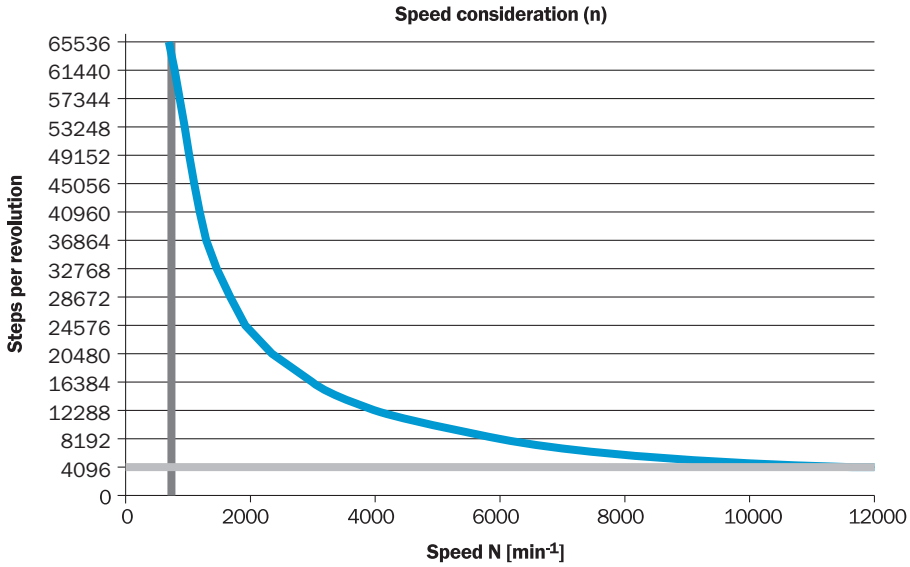
View of M23 male device connector

PIN, 8-pin, M12 male connector	PIN, 12-pin, M23 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V_{ss}	Explanation
1	6	Brown	¯A	COS–	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	¯B	SIN–	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	¯Z	¯Z	Signal wire
6	3	Violet	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection of the encoder
8	12	Red	$+U_s$	$+U_s$	Supply voltage (volt-free to housing)
–	9	–	n.c.	n.c.	Not assigned
–	2	–	n.c.	n.c.	Not assigned
–	11	–	n.c.	n.c.	Not assigned
–	7 [1]	–	0-SET [1]	n.c.	Set zero pulse [1]
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

[1] For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_s for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

Diagrams

Maximum revolution range



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