

DFS60B-T8PN10000

DFS60

INCREMENTAL ENCODERS





Ordering information

Туре	Part no.
DFS60B-T8PN10000	1078782

Other models and accessories → www.sick.com/DFS60

Illustration may differ



Detailed technical data

Safety-related parameters

MTTF _D (mean time to dangerous failure)	300 years (EN ISO 13849-1) 1)
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	10,000 ¹⁾
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°

¹⁾ See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL/HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	✓
Initialization time	32 ms, 30 ms ¹⁾
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.7 W (without load)

 $^{^{1)}}$ With mechanical zero pulse width.

Electronics

Connection type	Cable, 8-wire, universal, 10 m ¹⁾

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

 $^{^{2)}}$ Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

 $^{^{3)}}$ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

Supply voltage	4.5 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ^{2) 3)}

 $^{^{1)}}$ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

Mechanics

Mechanical design	Through hollow shaft
Shaft diameter	15 mm
Weight	+ 0.2 kg
Shaft material	Plastic
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.2 mm (axial)
Operating speed	≤ 6,000 min ^{-1 1)}
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{^{1)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side, cable connection (IEC 60529) IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +100 °C ¹⁾ -30 °C +100 °C ²⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $^{^{1)}}$ Stationary position of the cable.

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590

Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

 $^{^{3)}}$ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

²⁾ Flexible position of the cable.

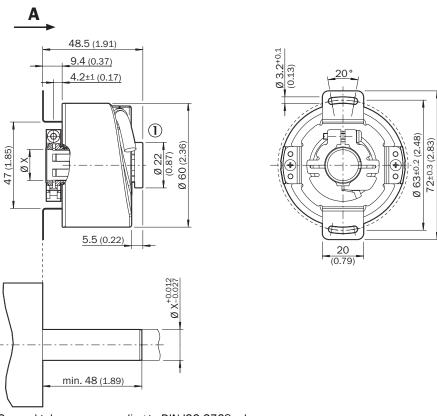
DFS60B-T8PN10000 | DFS60

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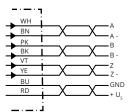
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, plastic hollow shaft clamping, cable



PIN assignment

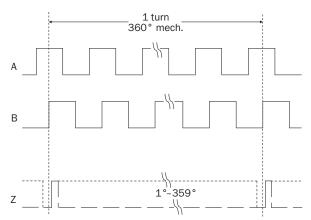


PIN Male connector M12, 8-pin	PIN Male connec- tor M23, 12-pin	Wire colors (ca- ble connection)	TTL/HTL signal	Sin/Cos 1.0 V _{PP}	Explanation
1	6	Brown	_A	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	_в	SIN-	Signal wire
4	8	Pink	В	SIN+	Signal wire
5	4	Yellow	_Z	_Z	Signal wire
6	3	Purple	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U _S	+U _S	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 1)	Orange	0-SET ¹⁾	N.c.	Set zero pulse
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

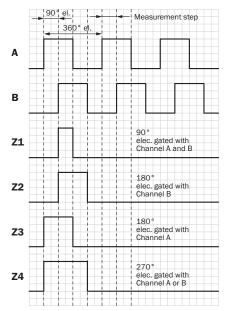
Diagrams

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Supply voltage	Output
4,5 V 32 V	TTL/HTL programmable

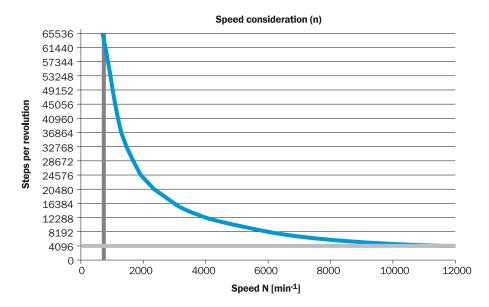
Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output	
4,5 V 32 V	TTL/HTL programmable	

Maximum revolution range



Recommended accessories

Other models and accessories → www.sick.com/DFS60

	Brief description	Туре	Part no.	
Flanges				
	Description: Standard stator coupling	BEF-DS00XFX	2056812	
Other mounting accessories				
	 Description: Clamping ring for metal hollow shaft^c Details: Metal 	BEF-KR-M	2064709	

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