



# DFS60S-TG0A01024

DFS60S Pro

**INCREMENTAL ENCODERS** 





## Ordering information

Туре	Part no.
DFS60S-TG0A01024	1069531

Other models and accessories → www.sick.com/DFS60S\_Pro

Illustration may differ



#### Detailed technical data

#### Safety-related parameters

carety relation parameters		
Safety integrity level	SIL 2 (IEC 61508), SILCL2 (IEC 62061) 1)	
Performance level	PL d (EN ISO 13849) 1)	
Category	3 (EN ISO 13849)	
PFH <sub>D</sub> : Probability of dangerous failure per hour	1.7 x 10 <sup>-8 2)</sup>	
T <sub>M</sub> (mission time)	20 years (EN ISO 13849)	
Safety-related measuring step	0.09°, Quadrature analysis	
Safety-related accuracy	± 0.09°	

<sup>1)</sup> For more detailed information on the exact configuration of your machine/unit, please consult your relevant SICK branch office.

#### Performance

Sine/cosine periods per revolution	1,024
Measuring step	0.3 ", For interpolation of the sine/cosine signals with e.g. 12 bit $^{1)}$
Integral non-linearity	Typ. $\pm$ 45 $^{\prime\prime}$ (without mechanical tension of the stator coupling)
Differential non-linearity	± 7 "

<sup>1)</sup> Not safety-related.

#### Interfaces

Communication interface	Incremental
Communication Interface detail	Sin/Cos 1)
Initialization time	50 ms <sup>2)</sup>
Output frequency	≤ 153.6 kHz

<sup>1) 1.0</sup> V<sub>SS</sub> (differential).

<sup>2)</sup> The values displayed apply to a diagnostic degree of coverage of 99%, which must be achieved by the external drive system and 95 °C operating temperature.

 $<sup>^{\</sup>rm 2)}\,{\rm Valid}$  signals can be read once this time has elapsed.

Power consumption	≤ 0.7 W (without load)
Load resistance	≥ 120 Ω

 $<sup>^{1)}</sup>$  1.0 V<sub>SS</sub> (differential).

#### Electrical data

Connection type	Male connector, M23, 12-pin, radial		
Supply voltage	4.5 32 V		
Reference signal, number	1		
Reference signal, position	90°, electronically, gated with Sinus and Cosinus		
Reverse polarity protection	✓		
Protection class	III (according to DIN EN 61140)		
Short-circuit protection of the outputs	<b>✓</b> ¹)		

 $<sup>^{(1)}</sup>$  Short-circuit to another channel or GND permitted for max. 30 s. In the case of U<sub>S</sub>  $\leq$  12 V additional short-circuit to U<sub>S</sub> permitted for max. 30 s.

#### Mechanical data

Mechanical design	Through hollow shaft		
Shaft diameter	14 mm With feather key groove		
Weight	Approx. 0.25 kg <sup>1)</sup>		
Shaft material	Stainless steel		
Flange material	Die-cast zinc		
Housing material	Aluminum die cast		
Start up torque	≤ 0.8 Ncm (+20 °C)		
Operating torque	≤ 0.6 Ncm (+20 °C)		
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)		
Permissible movement dynamic	± 0.05 mm (radial) ± 0.1 mm (axial)		
Operating speed	≤ 6,000 min <sup>-1 2)</sup>		
Moment of inertia of the rotor	56 gcm <sup>2</sup>		
Bearing lifetime	3.6 x 10 <sup>9</sup> revolutions <sup>3)</sup>		
Angular acceleration	≤ 500,000 rad/s²		

<sup>&</sup>lt;sup>1)</sup> Based on encoder with male connector.

#### Ambient data

EMC	According to EN 61000-6-2, EN 61000-6-3 and IEC 61326-3-1		
Enclosure rating	IP65 (IEC 60529) <sup>1)</sup>		
Permissible relative humidity	90 % (Condensation not permitted)		
Operating temperature range	-30 °C +95 °C <sup>2)</sup>		

 $<sup>^{1)}</sup>$  With male connector and mating connector fitted minimum IP65.

 $<sup>^{2)}</sup>$  Valid signals can be read once this time has elapsed.

 $<sup>^{2)}</sup>$  Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

 $<sup>^{</sup>m 3)}$  On maximum operating speed and temperature.

<sup>&</sup>lt;sup>2)</sup> Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

<sup>3)</sup> Checked to operation with vector length monitoring.

Storage temperature range	-30 °C +85 °C, without package	
<b>Resistance to shocks</b> 100 g, 6 ms (EN 60068-2-27) <sup>3)</sup>		
Resistance to vibration	10 g, 10 Hz 1,000 Hz (EN 60068-2-6)	

 $<sup>^{1)}\,\</sup>mathrm{With}$  male connector and mating connector fitted minimum IP65.

## Classifications

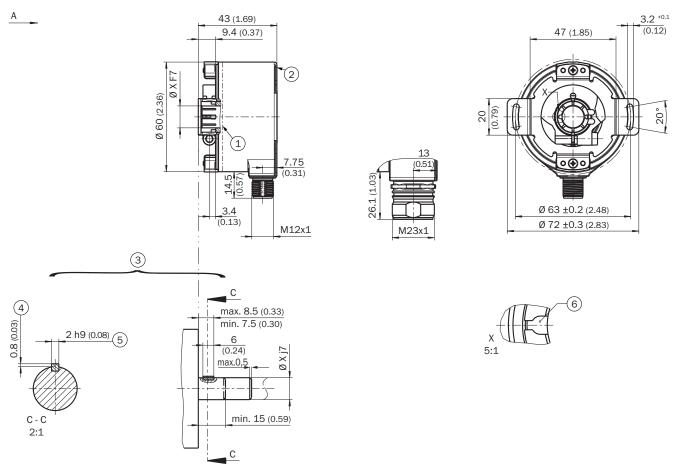
eCl@ss 5.0	27270501
eCl@ss 5.1.4	27270501
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCI@ss 7.0	27270501
eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCI@ss 9.0	27270501
eCl@ss 10.0	27270501
eCl@ss 11.0	27270501
eCl@ss 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

<sup>&</sup>lt;sup>2)</sup> Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

<sup>3)</sup> Checked to operation with vector length monitoring.

# Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, M12 and M23 radial male connector



General tolerances according to DIN ISO 2768-mk

- ① Operating temperature measuring point (freely selectable, around the housing surface area in each case, approx. 3 mm away from flange)
- ② Measuring point vibration (respectively at the housing face. approx. 3 mm away from the cover edge)
- 3 Attachment specifications
- 4 Max. 0.4 at Ø 5/8"
- ⑤ Feather key DIN 6885-A 2x2x6
- 6 Feather key groove

Shaft diameter XF7	Shaft diameter xj7
6 mm	Provided by customer
8 mm	
3/8″	
10 mm	
12 mm	
1/2"	
14 mm	
15 mm	
5/8″	

# PIN assignment

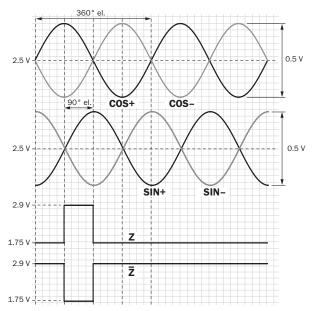


View of M23 male device connector on encoder

PIN Male connector M12, 8-pin	PIN Male connec- tor M23, 12-pin	Wire colors (ca- ble connection)	Signal	Explanation
1	6	Brown	- COS	Signal wire
2	5	White	+ COS	Signal wire
3	1	Black	- SIN	Signal wire
4	8	Pink	+ SIN	Signal wire
5	4	Yellow		Signal (do not use for safety operating mode)
6	3	Violet	Z	Signal (do not use for safety operating mode)
7	10	Blue	GND	Ground connection
8	12	Red	U <sub>S</sub>	Supply voltage (volt-free to housing)
-	9	-	N.C.	Not assigned
-	2	-	N.C.	Not assigned
-	11	-	N.C.	Not assigned
-	7	-	N.C.	Not assigned
Screen	Screen	Screen	Screen	Screen connected to encoder housing Screen connected to housing on encoder side. Connected to ground on control side.

# **Diagrams**

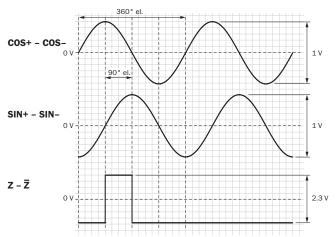
Signal SIN/COS before differential generation



For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

Signal	Interface signals	Signal before differ- ential generation At load 120 Ω	Signal offset
+ SIN - SIN + COS - COS	Analog, differential	0,5 V <sub>SS</sub> ± 20 %	2,5 V ± 10 %
Z Z_	Digital differential	Low: 1,75 V $\pm$ 15 %, High: 2,90 V $\pm$ 15 %	

Signal SIN/COS after differential generation



For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

Supply voltage	Output
4,5 V 5,5 V	Sin/Cos 1.0 V <sub>PP</sub>

# SICK AT A GLANCE

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For us, that is "Sensor Intelligence."

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