

DLS40E-BDGV00100

DLS40

INCREMENTAL ENCODERS





Ordering information

Туре	Part no.
DLS40E-BDGV00100	1132514

Illustration may differ

Other models and accessories → www.sick.com/DLS40



Detailed technical data

Safety-related parameters

MTTF _D (mean time to dangerous failure)	600 years (EN ISO 13849-1) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	100
Measuring step	90°, electric/pulses per revolution
Duty cycle	≤ 0.5 ± 10 %

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	3 channel
Output frequency	≤ 150 kHz
Load current	≤ 30 mA
Power consumption	≤ 2 W (without load)

Electrical data

Connection type	Cable, 5-wire, radial, 2 m
Supply voltage	10 27 V
Reference signal, number	1
Reverse polarity protection	✓
Short-circuit protection of the outputs	√ ¹⁾

¹⁾ Protection against short circuit to GND and U_{S.} Short-circuit resistance is only guaranteed when Us and GND are connected correctly.

Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	10 mm
Weight	Approx. 170 g ¹⁾

 $^{^{1)}}$ Relates to encoders with 2 m cable connection.

 $^{^{2)}}$ Allow for self-heating of 1.3 K per 1,000 rpm when designing the operating temperature range.

 $^{^{}m 3)}$ No permanent operation. Decreasing signal quality.

Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Material, cable	PVC
Start up torque	0.5 Ncm
Operating torque	0.3 Ncm
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.2 mm (axial)
Operating speed	6,000 min ^{-1 2)}
Maximum operating speed	≤ 8,000 min ^{-1 3)}
Moment of inertia of the rotor	24.6 gcm ²
Bearing lifetime	2.0 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{^{1)}}$ Relates to encoders with 2 m cable connection.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-10 °C +70 °C
Storage temperature range	-25 °C +85 °C
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)

Classifications

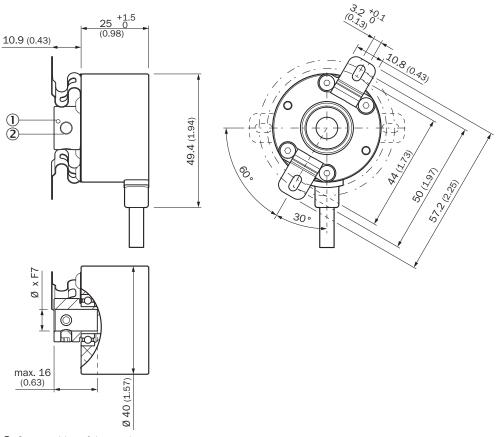
ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

²⁾ Allow for self-heating of 1.3 K per 1,000 rpm when designing the operating temperature range.

³⁾ No permanent operation. Decreasing signal quality.

Dimensional drawing (Dimensions in mm (inch))

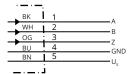
Blind hollow shaft



- ① Start position of the Z-pulse
- ② 2x M4 threaded pin hex key screw size 2.0

Type Blind hollow shaft	Shaft diameter XF7
DLS40E-BAxxxxxxx	6 mm
DLS40E-BBxxxxxxx	8 mm
DLS40E-BDxxxxxxx	10 mm
DLS40E-BExxxxxxx	12 mm

PIN assignment

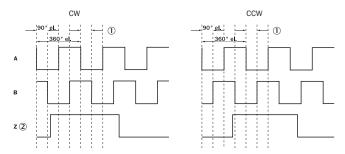


Wire colors (ca- ble connection)	Signal	Description
Brown	U_S	Supply voltage
Blue	GND	Ground connection
Black	A	Signal cable

Wire colors (ca- ble connection)	Signal	Description
White	В	Signal cable
Orange	Z	Signal cable

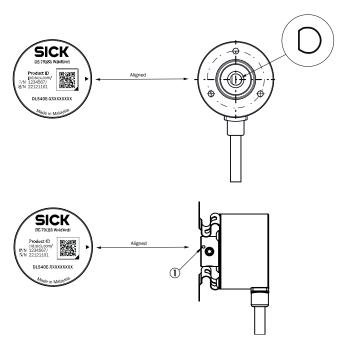
Diagrams

HTL/Push pull



- ① Measuring step
- ② Only as reference

Operation note



You can see the position with the mark on the rear side of the encoder ${\tt \textcircled{1}}$ Zero pulse mark on housing

SICK AT A GLANCE

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