

# DUS60E-BKKKOAAA

**INCREMENTAL ENCODERS** 



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Туре	Part no.
DUS60E-BKKK0AAA	1104376

Other models and accessories -> www.sick.com/DUS60



## Detailed technical data

#### Performance

Measuring step90°, electric/pulses per revolutionMeasuring step deviation418° / pulses per revolutionMeasuring step deviationMeasuring step deviation x 3Error limits605 ± 5%Duty cycle505 ± 5%Communication interfaceIncrementalCommunication interfaceIncrementalParameterising data0Output functionAnd BoutputInitialization time600 kHzCompany function600 kHzDuty function600 kHzOutput fing ueront610 kHzDevencement510 kHzDistich parameters510 kHzPower consumption610 kHzPulses per revolution610 kHzOutput time610 kHzMeasure time610 kHzPulses per revolution610 kHzOutput time610 kHzCompany function610 kHzPulses per revolution610 kHzOutput time610 kHzCompany function610 kHz <th></th> <th></th>		
Error limits       Measuring step deviation × 3         Duty cycle       <0.5 ± 5 %         Interfaces       Incremental         Communication interface       Incremental         Communication Interface detail       TL / HTL <sup>1</sup> Parameterising data       DP switch, selectable output         Output function       And B output         Initialization time       <5 ms <sup>2</sup> )         Output frequency       <60 kHz         Ioad current       <100 mA (without load)         Operating current       <125 W (without load)         Power consumption       <125 W (without load)         Pless per revoluin	Measuring step	90°, electric/pulses per revolution
Duty cycle       ≤ 0.5 ± 5 %         Ditterfaces       Incrementation interface         Communication interface detail       Incrementation interface         Communication Interface detail       TL / HTL <sup>1</sup> Parameterising data       DIP switch, selectable output         Output function       And B output         Initialization time       < 5 ms <sup>2</sup> Output frequency       400 kHz         Ioda current       < 300 mA, per channel         Operating current       < 120 mA (without load)         Power consumption       < 120 tw (without load)         Pubes per revolution	Measuring step deviation	± 18° / pulses per revolution
Interfaces       Incremental         Communication interface detail       Incremental         Communication Interface detail       TL / HTL <sup>1</sup> Parameterising data       DIP switch, selectable output         Output function       A and B output         Initialization time       < 5 ms <sup>2</sup> )         Output frequency       + 60 kHz         Iod current       < 30 mA, per channel         Operating current       < 120 mA (without load)         Power consumption       < 1.25 W (without load)         IP switch parameters	Error limits	Measuring step deviation x 3
Communication interface       Incemental         Communication Interface detail       Inc / Incl / Inc	Duty cycle	≤ 0.5 ± 5 %
Communication Interface detail       ال ( HTL <sup>1</sup> )         Parameterising data       DP switch selectable output         Output function       A and B output         Initialization time       < 5 ms <sup>2</sup> Output frequency       + 0 kHz         Load current       < 30 mA, per channel         Operating current       = 10 current ( Step Sentence)         Power consumption       = 12 current ( Step Sentence)         Power consumption       = 12 current ( Step Sentence)         Power consumption       = 12 current ( Step Sentence)         Pubers per sentence	nterfaces	
Parameterising data       DP switch selectable output         Output function       And B output         Initialization time       < 5 ms <sup>2</sup> Output frequency       + 60 kHz         Load current       < 30 mA, per channel         Operating current       < 120 mA (without load)         Power consumption       < 120 Without load)         Pubes per newber          Pubes per newber	Communication interface	Incremental
Output function       A and B output         Initialization time       < 5 ms <sup>2</sup> Output frequency       < 60 kHz         Load current       < 30 mA, per channel         Operating current       < 120 mA (without load)         Power consumption       < 1.25 W (without load)         Pluses per revolution	Communication Interface detail	TTL / HTL <sup>1)</sup>
Initialization time       < 5 ms <sup>2</sup> Output frequency       < 60 kHz         Load current       < 30 mA, per channel         Operating current       < 120 mA (without load)         Power consumption       < 125 W (without load)         Plassement          Pulses per une volume	Parameterising data	DIP switch, selectable output
Output frequency     + 60 kHz       Load current     ≤ 30 mA, per channel       Operating current     ≤ 120 mA (without load)       Power consumption     ≤ 1.25 W (without load)       DIP switch parameters     ✓	Output function	A and B output
Load current     ≤ 30 mA, per channel       Operating current     ≤ 120 mA (without load)       Power consumption     ≤ 1.25 W (without load)       DIP switch parameters     ✓	Initialization time	< 5 ms <sup>2)</sup>
Operating current     ≤ 120 mA (without load)       Power consumption     ≤ 1.25 W (without load)       DIP switch parameters        Pulses per revolution     ✓	Output frequency	+ 60 kHz
Power consumption     ≤ 1.25 W (without load)       DIP switch parameters     Pulses per revolution	Load current	≤ 30 mA, per channel
DIP switch parameters Pulses per revolution	Operating current	$\leq$ 120 mA (without load)
Pulses per revolution	Power consumption	$\leq$ 1.25 W (without load)
	DIP switch parameters	
Output voltage 🖌	Pulses per revolution	✓
	Output voltage	1
Direction of rotation 🗸	Direction of rotation	4
Configuration switches 2400 PPR values, direction selection, TTL/HTL selectable	Configuration switches	2400 PPR values, direction selection, TTL/HTL selectable

<sup>1)</sup> The output is not selectable for DIP switch configurations E, F, and G. The output voltage value is dependent on the supply voltage.

 $^{\rm 2)}$  Valid positional data can be read once this time has elapsed.

#### Electrical data

Connection type	Cable, 8-wire, universal, 1.5 m <sup>1)</sup>
Supply voltage	4.75 30 V

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

2) This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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Reference signal, number	1
Reference signal, position	180°, electric, gated with A
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓
MTTFd: mean time to dangerous failure	275 years (EN ISO 13849-1) <sup>2)</sup>

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

<sup>2)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	1/4"
Flange type / stator coupling	2-point stator coupling, slot, hole diameter 63 mm – 83 mm
Weight	0.25 kg <sup>1)</sup>
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Material, cable	PVC
Start up torque	0.5 Ncm (+20 °C)
Operating torque	0.4 Ncm (+20 °C)
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.2 mm (axial)
Operating speed	1,500 min <sup>-1</sup>
Moment of inertia of the rotor	50 gcm <sup>2</sup>
Bearing lifetime	3.6 x 10 <sup>9</sup> revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{1)}\,\mathrm{Based}$  on encoder with male connector.

#### Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65 <sup>1)</sup>
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-30 °C +90 °C
Storage temperature range	-40 °C +75 °C
Resistance to shocks	100 g (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $^{1)}$  When the mating connector is installed and the DIP switch door is sealed with the encoder housing.

### Classifications

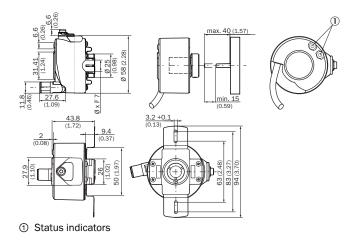
eCl@ss 5.0	27270501
eCl@ss 5.1.4	27270501
eCl@ss 6.0	27270590

INCREMENTAL ENCODERS

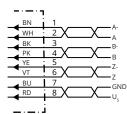
eCl@ss 6.2	27270590
eCl@ss 7.0	27270501
eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCl@ss 9.0	27270501
eCl@ss 10.0	27270501
eCl@ss 11.0	27270501
eCl@ss 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

## Dimensional drawing (Dimensions in mm (inch))

Blind hollow shaft



## **PIN** assignment



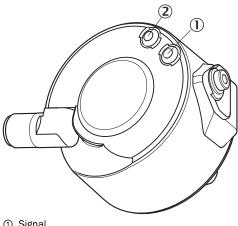
Wire colors (ca-	Male con-	Male con-		Output function			
ble connection)	nector M12, 4-pin	nector M12, 8-pin	Α	В	С	D	
Brown	-	1	A-	CW-	A-	A-	Signal
White	4	2	А	CW	А	А	Signal

INCREMENTAL ENCODERS

Wire colors (ca-	Male con- Male con-					Explanation	
ble connection)	nector M12, 4-pin	nector M12, 8-pin	A	В	С	D	
Black	-	3	B-	CCW-	Direction-	B-	Signal
Pink	2	4	В	ccw	Direction	Fault (M12, 4- pin) B (M12, 8- pin and cable connection)	Signal
Yellow	-	5	Z-	Fault-	Fault-	Fault-	Signal
Violet	-	6	Z	Fault	Fault	Fault	Signal
Blue	3	7	GND	GND	GND	GND	Ground con- nection
Red	1	8	U <sub>S</sub>	U <sub>S</sub>	U <sub>S</sub>	U <sub>S</sub>	Supply volt- age
-	-	-	Case	Case	Case	Case	Earth fault protection
Shielding	-	-	Shielding	Shielding	Shielding	Shielding	Shielding

## Adjustments

Status indicator LED



Signal
 Fault/Power

## **Recommended accessories**

Other models and accessories → www.sick.com/DUS60

	Brief description	Туре	Part no.
Plug connecto	rs and cables		
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 2 m	DOL-1208-G02MAC1	6032866

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	Brief description	Туре	Part no.
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m	DOL-1208-G05MAC1	6032867
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m	DOL-1208-G10MAC1	6032868
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 20 m	DOL-1208-G20MAC1	6032869
	Head A: female connector, M12, 4-pin, straight, A-coded Head B: Flying leads Cable: Sensor/actuator cable, PUR, halogen-free, shielded, 2 m	YF2A24- 020UB4XLEAX	2105499
Ū	Head A: female connector, M12, 4-pin, straight, A-coded Head B: Flying leads Cable: Sensor/actuator cable, PUR, halogen-free, shielded, 5 m	YF2A24- 050UB4XLEAX	2095729
	Head A: female connector, M12, 4-pin, straight, A-coded Head B: Flying leads Cable: Sensor/actuator cable, PUR, halogen-free, shielded, 10 m	YF2A24- 100UB4XLEAX	2095730
	Head A: female connector, M12, 4-pin, straight, A-coded Head B: Flying leads Cable: Sensor/actuator cable, PUR, halogen-free, shielded, 20 m	YF2A24- 200UB4XLEAX	2105497
	Head A: female connector, M12, 5-pin, straight Cable: CANopen, DeviceNet™, shielded	DOS-1205-GA	6027534
	Head A: female connector, M12, 8-pin, straight, A-coded Cable: Incremental, SSI, shielded	DOS-1208-GA01	6045001

# SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

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Online data sheet

