



MOTOR FEEDBACK SYSTEMS



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Туре	Part no.
SFM60-HLBT1K02	1068998

M3 mounting screws for stator coupling not included with delivery.

Other models and accessories -> www.sick.com/SFS_SFM60



Detailed technical data

Features

Items supplied	M3 mounting screws for stator coupling not included with delivery.	
Safety-related parameters		
MTTF_{D} (mean time to dangerous failure)	230 years (EN ISO 13849) ¹⁾	

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Sine/cosine periods per revolution	1,024
Number of the absolute ascertainable revo- lutions	4,096
Total number of steps	134,217,728
Measuring step	$0.3\ensuremath{^{\prime\prime}}$ For interpolation of the sine/cosine signals with, e. g., 12 bits
Integral non-linearity	Typ. \pm 45 ″, Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling
Differential non-linearity	\pm 7 ", Non-linearity within a sine/cosine period
Operating speed	\leq 6,000 min ⁻¹ , up to which the absolute position can be reliably produced
Available memory area	1,792 Byte
System accuracy	± 52 ″
Interfaces	

Type of code for the absolute value	Binary
Code sequence	Rising, For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE®

Electrical data

Connection type	Male connector, M12, 8-pin, radial
Supply voltage	7 V DC 12 V DC
Recommended supply voltage	8 V DC
Current consumption	< 80 mA (without load)

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Output frequency for sine/cosine signals	≤ 200 kHz
Mechanical data	
Shaft version	Through hollow shaft
Shaft diameter	10 mm
Shaft material	Stainless steel
Flange material	Zinc diecast
Housing material	Aluminum die cast
Flange type / stator coupling	Stator coupling (BEF-DS01DFS/VFS)
Dimensions	See dimensional drawing
Weight	≤ 0.25 kg
Moment of inertia of the rotor	40 gcm ²
Operating speed	≤ 9,000 min ^{-1 1)}
Angular acceleration	≤ 500,000 rad/s²
Operating torque	0.6 Ncm (+20 °C)
Start up torque	+ 0.8 Ncm (+20 °C)
Permissible movement static	± 0.3 mm, ± 0.5 mm radial, axial
Permissible movement dynamic	± 0.05 mm radial ± 0.2 mm axial
Life of ball bearings	3.6 x 10 ⁹ revolutions

 $^{1)}\,\mathrm{Allow}$ for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

Operating temperature range	-40 °C +115 °C
Storage temperature range	-40 °C +115 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2 and EN 61000-6-3 $^{1)}$
Enclosure rating	IP65, with mating connector inserted (IEC 60529)

¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

Classifications

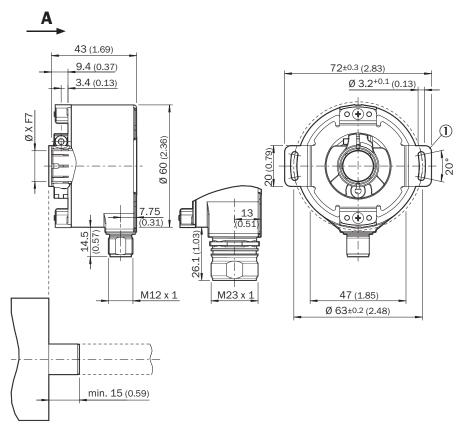
ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805

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ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, male connector - standard system

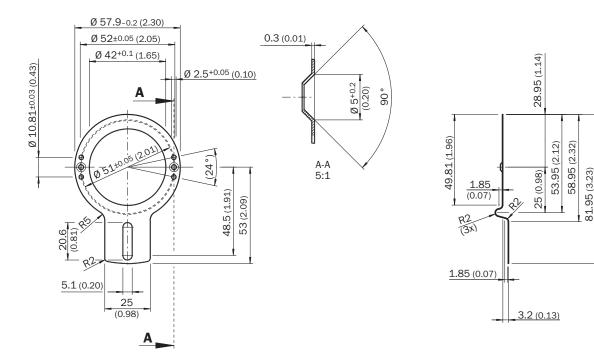


General tolerances according to DIN ISO 2768-mk

① Dimensional drawing of the stator coupling may differ depending on the variant. Please also refer to the dimensional drawing of the stator coupling.

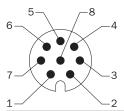
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BEF-DS01DFS/VFS



PIN assignment

View of the M12 male connector plug-in face

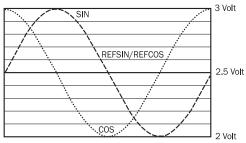


PIN	Signal	Explanation
1	REFSIN	Process data channel
2	+ SIN	Process data channel
3	REFCOS	Process data channel
4	+ COS	Process data channel
5	Data +	Parameter channel RS 485
6	Data -	Parameter channel RS 485
7	GND	Ground connection
8	U _S	Supply voltage
Housing	Screen	Screen connected to encoder housing

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Diagrams

Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = 360 °: 1024

Operation note

Charactersitics applicable to all permissible environmental conditions

Signal	Values/unit
Signal peak, peak V _{ss} of SIN, COS	0.9 V 1.1 V
Signal offset REFSIN, REFCOS	2.2 V 2.8 V

Model-specific settings

	SFS	SFM
Model ID (command 52h)	22h	27h
Free E ² PROM [bytes]	128/1.792	128/1.792
Address	40h	40h
Mode_485	E4h	E4h
Codes 0 to 3	55h	55h
Counter	0	0

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Overview of supported commands for $\mathsf{HIPERFACE}^{\circledast}$

			SFS	SFM
Command byte	Function	Code 0 ¹⁾	Comment	Comment
42h	Read position	-		
43h	Set position			
44h	Read analog value		Channel number 48h	Channel number 48h
			Temperature [°C]	Temperature [°C]
46h	Read counter			
47h	Increase counter			
49h	Delete counter	-		
4Ah	Read data			
4Bh	Store data			
4Ch	Determine status of a data field			
4Dh	Create data field			
4Eh	Determine available memory area			
4Fh	Change access code			
50h	Read encoder status			
52h	Read out type label		Encoder type = 22h	Encoder type = 22h
53h	Encoder reset			
55h	Allocate encoder address	-		
56h	Read serial number and program version			
57h	Configure serial interface	-		

¹⁾ The commands thus marked include the parameter 'Code 0'. Code 0 is a byte inserted into the protocol to provide additional protection of vital system parameters against accidental overwriting. When the device is supplied, 'Code 0' = 55h.

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Overview of status messages for HIPERFACE®

	Status code	Description	SFS	SFM
Error type	00h	The encoder has not detected any faults	-	•
	01h	Incorrect alignment data	-	-
	02h	Incorrect internal angular offset	-	
Initialization	03h	Data field partitioning table destroyed	-	-
mittalization	04h	Analog limit values not available	-	-
	05h	Internal I2C bus inoperative	-	-
	06h	Internal checksum error	-	-
	07h	Encoder reset occurred as a result of program monitoring	-	
	09h	Parity error	-	-
Protocol	0Ah	Checksum of transmitted data is incorrect	-	-
FIOLOCOI	0Bh	Unknown command code	-	-
	0Ch	Number of transmitted data is incorrect	-	-
	0Dh	Transmitted command argument is not allowed	-	-
	0Eh	The selected data field may not be written to	-	
	0Fh	Incorrect access code	-	
Data	10h	Size of specified data field cannot be changed	-	-
	11h	Specified word address lies outside the data field	-	-
	12h	Access to non-existent data field	-	
	01h	Analog signals outside specification	-	
	1Fh	Speed too high, no position formation possible	-	-
Position	20h	Singleturn position unreliable	-	
FUSICION	21h	Multiturn position error		
	22h	Multiturn position error		
	23h	Multiturn position error		-
	1Ch	Value monitoring of the analog signals (process data)	-	-
Other	1Dh	Transmitter current critical (contamination, transmitter breakage)	•	•
	1Eh	Encoder temperature critical	-	
	08h	Counter overflow	-	

Recommended accessories

Other models and accessories → www.sick.com/SFS_SFM60

	Brief description	Туре	Part no.			
Programming and configuration tools						
60 10	SVip® LAN programming tool for all motor feedback systems	PGT-11-S LAN	1057324			
Flanges						
	One-sided stator coupling, slot, slot radius 33 mm to 48.5 mm, slot width 5.1 mm	BEF-DS01DFS/VFS	2047428			
	One-sided stator coupling, slot, slot radius 32.25 mm to 141.75 mm, slot width 5.1 mm	BEF-DS02DFS/VFS	2047430			

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	Brief description	Туре	Part no.
đ	One-sided stator coupling, slot, slot radius 33 mm to 211.9 mm, slot width 5.1 mm	BEF-DS03DFS/VFS	2047431
	Stator coupling, 16.5 mm high	BEF-DS05XFX	2057423
Ŵ	Stator coupling with hole circle diameter Ø72 mm	BEF-DS07XFX	2059368

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