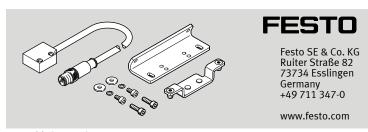
# ELGA-...-M1/-M2 Displacement encoder



Assembly instructions

8120866 2020-03a [8120868]



Translation of the original instructions

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# 1 Applicable Documents

All available documents for the product → www.festo.com/sp.

Document	Product	Contents	
Instructions	ELGA	Operating	

Tab. 1

### 2 Safety

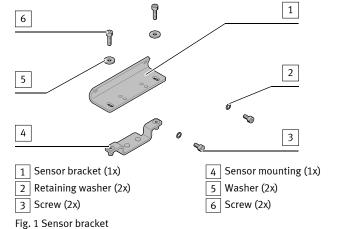
## 2.1 Safety Instructions

- Only mount the product on components that are in a condition to be safely operated.
- $\;$  Observe tightening torques. Unless otherwise specified, the tolerance is  $\pm$  20 %.
- Avoid external magnetic fields (> 64 mT) on the surface of the magnetic tape, otherwise the coding will be destroyed.
- Avoid external magnetic fields (> 1 mT) at the sensor, otherwise the system accuracy will be reduced.

# 2.2 Intended Use

Sensing of the slide position of an axis ELGA -...- BS / -TB-KF or ELGA -...- TB-RF.

# 3 Scope of Delivery



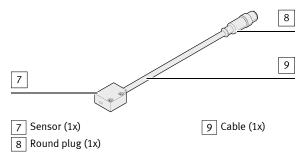


Fig. 2 Measuring unit

## 4 Assembly

## 4.1 Requirement

- Use axis with feature M1/M2.

# 4.2 Assembly of Displacement Encoder

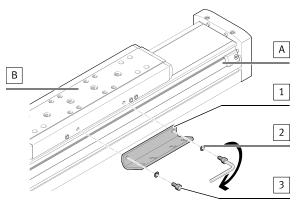


Fig. 3 Mount the sensor bracket

• Mount sensor bracket 1 with the retaining washers 2 and the screws 3 on the slide (B).

ELGA		70/80	120/150	
3	Screw		M4x8	M5x10
		[Nm]	5	5.9

Tab. 2 Tightening Torques

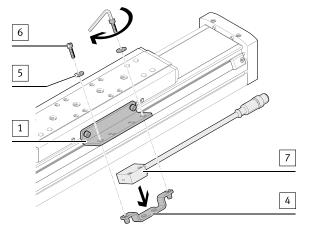


Fig. 4 Mount the measuring unit

- 1. Position the sensor head 7 in the sensor mounting 4.
- Place the sensor mounting 4 and sensor head 7 on the sensor bracket 1.
   Sensing distance S: → 7 Technical Data.
- Mount sensor mounting 4 with the washers 5 and the screws 6. Tightening torque: 3.5 Nm

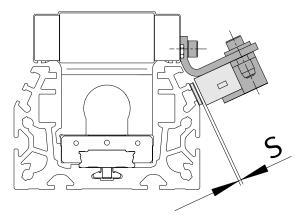


Fig. 5 Observe sensing distance

#### 4.3 Strain Relief

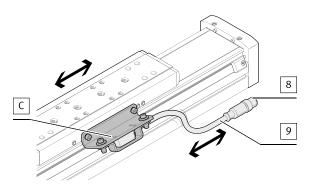


Fig. 6 Use strain relief on cable

- 1. Ensure sufficient strain relief for the cable  $\boxed{9}$ , e.g. with cable binders. The four drill holes (C) are provided for this purpose.
- Connect plug 8 to the matching socket. Tightening torque: 0.25 Nm ± 10% Observe the permissible bending radius R and the permissible ambient temperature with flexible cable installation → 7 Technical Data.

#### **Contact Assignment** 5

Plug M12 8-pin, A-coded	Pin	Signal
2	1	/B
3 ~ 0	2	/A
$\frac{3}{+} + \frac{8}{4}$	3	0 V (GND)
4(+++)1	4	В
'\+ ; + / *	5	VCC
5 7	6	N
6	7	0
	8	/N
	Housing	Shield

Tab. 3 Contact Assignment

The displacement encoder and the magnetic tape (A) are maintenance-free. In the event of damage, replace the components 

www.festo.com/spareparts.

# **Technical Data**

Measuring unit			M1	M2
Sensing distance	S	[mm]	0.1 2	
Cable bending radius	R	[mm]	≥ 60	
Cable length		[m]	≤ 25	
Permitted controllers			CMM	CMM CMGA
Humidity			≤ 80% (non-condensing)	
Note on materials			Contains paint-wetting impairment substances <sup>1)</sup>	
Measuring principle			Magnetic, incremental, 4x edge control	
Signal output			Proportional to speed	
Interpolation rate			2000	500
Resolution [ $\mu m$ ] at travel speed $\leq 4 \ m/s$		2.5	10	

Measuring unit		M1	M2	
Repetition accuracy	Incre- ment	±1		
System precision at 20 °C	[µm]	±(25 + 20 x measuring length in m)		
Travel speed with CMMP-AS	[m/s]	≤ 4	≤ 4	
Travel speed with CMGA	[m/s]	≤ 1	≤ 4	
Reference signal (N/N)		Cyclical, every 5 mm		
Weight	[g]	40		
Acceleration	[m/s <sup>2</sup> ]	≤ 50		
Outputs		5 V TTL line driver, alternating, resistant to sustained short circuit		
Supply voltage				
Supply voltage DC	[V DC]	5 ± 2.5%		
Residual ripple	[mV]	< 50		
Current consumption	[mA]	≤ 200		
Degree of protection				
Sensor head		IP67		
Plug		IP64 in mounted status		
Temperature			<u> </u>	
Storage temperature	[°C]	-25 +85		
Ambient temperature with flexible cable installation	[°C]	-10 +70		

1) PWIS = paint-wetting impairment substances

Tab. 4 Technical Data